## Field Precision LLC

# Trak 8.0 <br> Electron/Ion Gun Design and Charged-particle Dynamics 

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Figure 1: Screenshot - Trak in the orbit plotting mode.

## 1 Introduction

### 1.1 Program functions

Trak is a versatile program for charged-particle optics. Applications include electron and ion guns, particle accelerators, ion sources, microwave sources, acceleration columns, electrostatic and magnetostatic lenses, vacuum tubes, and electro-optical devices. Trak operates in conjunction with field solution programs of the TriComp series. The program requires Mesh (the TriComp universal mesh generator) along with EStat and/or PerMag to create field input files. You should be familiar with mesh generation and field solution procedures before using Trak. The package includes GenDist, a utility for creating and analyzing particle distributions.

This manual concentrates on procedures to run Trak and does not give detailed explanations of the physics of charged-particle beams. Two texts written by the program author are supplied with the package. They provide a comprehensive overview of charged-particle optics:

- S. Humphries, Jr., Principles of Charged Particle Acceleration (Wiley, New York, 1986).
- S. Humphries, Jr., Charged Particle Beams (Wiley, New York, 1990).

The second work discusses beam distributions, emittance, beam-generated fields, propagation of high-current beams, the design of electron and ion guns and other topics. Techniques for electric and magnetic field solutions on a conformal triangular mesh are discussed in
S. Humphries, Jr., Field Solutions on Computers (CRC Press, Boca Raton, 1997).

### 1.2 Learning Trak

Trak is one of the most powerful tools available for the designing charged-particle guns and transport devices. Capabilities include mixed source and space-charge-limited emission, selfconsistent field emission, advanced techniques for magnetic field created by relativistic beams, and determination of an ideal plasma meniscus shape for ion emission. The extensive features call for a rich command language and a thick instruction manual. To be realistic, it is unlikely that you can use the program effectively without reading some of the manual. On the other hand, we have included many features to make the learning process as painless as possible:

- This manual is available from within the program. There is an index and advanced topics are clearly delineated.
- You can use interactive dialogs to set up program inputs for most calculations. It is easy to add refinements and changes later.
- We included input files for a variety of prepared examples. They cover the full spectrum of charged-particle applications and may serve as a template for your application.

To learn the program quickly, we suggest the follow sequence of activities:

- Read the next section carefully to understand the basic organization of a Trak simulation and the associated data files.
- Follow the walkthrough example of Chap. 2. The exercise introduces the fundamental tools you will need for you own simulations.
- Browse Chaps. 3 and 4. Chapter 3 describes how to use interactive dialogs to prepare runs, while Chap. 4 covers commands in the main Trak menu to control a calculation.
- Scan Chapter 5, which describes Trak features for plots of orbit and field information.
- Run some of the supplied examples. Try making small small changes to the geometries, material properties and particle distributions.
- As you gain experience, you will want to employ advanced capabilities. For example, you can include multiple emission surfaces in a calculation or set some materials to act as secondary-electron emitters. Advanced features are invoked by adding commands directly to the input script.
- Chapters on advanced features are organized by topic. Chapters 6 and 7 cover script commands to load and to control electric and magnetic field information. For example, you can add specified temporal modulations to fields.
- Chapters 8 through 14 describe advanced techniques for the calculation modes of Trak. Chapter 8 covers single-particle tracking in specified fields. Chapter 9 documents commands for precision tracing of electric field lines for applications such as ion mobility spectrometry.
- Chapter 10 summarizes commands for an advanced program mode where the space-charge of high-current beams contributes to the total electric field solution. In this mode, Trak accurately models self-consistent Child-law emission from cathodes. Chapter 11 applies to high-current relativistic beams where contributions from particles and current on electrodes are combined to find both self-consistent electric and magnetic fields.
- Chapter 12 covers self-consistent field emission of electrons for applications to vacuum microelectronics.
- Chapter 13 describes the unique Trak capability to directly calculate the ideal beam current and emission surface shape for ion extraction from a free plasma boundary.
- Chapter 14 describes commands to control electron secondary emission from metal surfaces. The capability is useful to model electron collectors and multipactor effects in high-power microwave sources.
- Finally, Chapter 15 summarizes advanced diagnostic capabilities of the code, including statistical analysis of beam distributions.
- The Trak package includes GenDist, a utility for preparing particle input files for Trak and other Field Precision programs. GenDist also has extensive routines for statistical analysis and plots of distributions created by Trak. The features of the program are described in a separate manual.


### 1.3 Program organization

Trak calculations generally involve the following steps:

1. Define the system geometry for an electric and/or magnetic field solution. The easiest approach is to use the drawing editor of Mesh. You can also use a text editor for direct input of boundary vectors. This activity creates Mesh input files with names of the form FPrefix.MIN for the electric and/or magnetic field solution.
2. Use Mesh to process the vector information to generate one or two conformal triangular meshes recorded in files with names of the form FPrefix.MOU. Trak can handle independent meshes for electric and magnetic fields that overlap a common region of space.
3. Define the properties of materials in the solution using the script-generation dialogs of EStat and/or PerMag. The resulting files have names of the form FPrefix.EIN and/or FPrefix.PIN for the solution programs.

Table 1: Trak files

| Name | Function |
| :--- | :--- |
| MName.MIN | Mesh input script for the electric and/or magnetic field <br> solution |
| MName.MOU | Mesh output (node locations and element identifies) |
| EName.EIN | EStat input script (run control and material proper- <br> ties) |
| EName.EOU | EStat output file (node locations and electrostatic po- <br> tential) |
| BName.PIN | PerMag input script (run control and material prop- <br> erties) |
| BName.POU | PerMag output file (node locations and vector poten- <br> tial) |
| TName.TIN | Trak script (program control, field sources, particle in- <br> put parameters) |
| Name.PRT | Optional Trak input file of initial particle parameters |
| TName.TLS | Trak listing (assorted quantitative information on the <br> run sequence and particle properties) |
| TName.TOU | Trak orbit file (particle positions to create plots) |
| Name.PRT | Optional Trak output file listing particle parameters <br> at a stopping or diagnostic plane |

4. Run EStat and/or PerMag to create input field solutions. The solution files FPrefix.EOU and FPrefix.POU contain complete mesh information as well as values of electrostatic or vector potential. Trak uses the information to compute $\mathbf{E}$ or $\mathbf{B}$ along particle trajectories. The program can also use the mesh information to determine if a particle strikes a material object (i.e., stopping conditions).
5. Decide on a calculation mode and use the interactive dialogs in Trak to prepare an input script FPrefix.TIN to control the run.
6. Run Trak to determine particle trajectories and (optionally) electric field modifications to include contributions of space-charge.
7. Use Trak to create orbit/field plots or GenDist to analyze output particle distributions.

The procedure involves many steps and many files - it may appear overly complex for simple benchmark calculations. The step-by-step approach with records of intermediate results rewards your effort in real-world applications. In the end, you have a complete record of all components of the solution, making it easy to reconstruct or to modify simulations. For orientation, Table 1 lists the file types that may appear in the Trak calculation. Note that the suffixes indicate the file function.

### 1.4 Some calculation basics

Trak calculates the orbits of point charged particles moving through electric and magnetic fields. These fields may result from external charges and currents (such as the charge induced on biased metal electrodes), surface charges in nearby dielectrics, or current in magnet coils. Such fields are called applied fieldsindexapplied fields. For low-intensity beams, it is sufficient to determine the applied fields and then to track any number of particle orbits in space. We use the term single-particle orbitsindexsingle-particle orbits when the fields created by the charge and effective current of the particles are negligible. In this case, particle orbits are independent of each another and it is unnecessary to modify the applied field to reflect the presence of the beam.

Field evaluations and orbit calculations in Trak are entirely numerical. Field calculations employ the finite-element method. Here, a bounded spatial region is divided into small segments - the TriComp programs use elements with triangular cross sections. The sizes and shapes of the triangles are adjusted to fit the boundaries of physical objects like electrodes. The spatial distribution of the set of triangle nodes (vertices) is called the computational mesh. In electrostatic calculations with EStat, the potential is determined at the nodes and the material characteristics (such dielectric constant, space charge, or constant potential) are assigned to the triangle volumes. A Trak run may also include an independent applied magnetic field solution created with PerMag. The solution may have a different computational mesh fitted to the boundaries of magnetic objects (such as coils or ferrites). The magnetic solution consists of values of vector potential at the nodes. A single-particle orbit calculation is conceptually simple. The orbit advances in small time steps. At any time, the program must identify the element that contains the particle. With this knowledge it is possible to collect potential values at neighboring nodes and take a spatial derivative to estimate electric fields. Similarly, a knowledge of the occupied triangle in the magnetic mesh leads to the magnetic fields at the particle position. Given the fields and the initial particle momentum, we can advance the orbit. We can also check whether the particle is outside the mesh or in a non-vacuum element in order to stop the calculation. A Trak calculation always follows an EStat and/or PerMag solution. Even if there is no applied field, we need to create a computational mesh for the calculation of beam-generated fields.

TriComp solution programs handle fields that vary in two dimensions in either cylindrical structures (variation in $r$ and $z$, uniform in $\theta$ ) or planar structures (variation in $x$ and $y$, infinite length along $z$ ). Trak computes particle orbits in three-dimensional Cartesian coordinates $(x, y, z)$ using the two-dimensional field components available from the solution programs. For rectangular problems, the non-zero field components are $E_{x}$ and $E_{y}$ or $B_{x}$ and $B_{y}$. Cylindrical solutions yield the components $E_{r}$ and $E_{z}$ or $B_{r}$ and $B_{z}$. The radial components are used to derive the Cartesian field components according to:

$$
\begin{align*}
E_{x}(x, y, z) & =E_{r}(r, z)(x / r),  \tag{1}\\
E_{y}(x, y, z) & =E_{r}(r, z)(y / r),  \tag{2}\\
B_{x}(x, y, z) & =B_{r}(r, z)(x / r),  \tag{3}\\
B_{y}(x, y, z) & =B_{r}(r, z)(y / r) . \tag{4}
\end{align*}
$$

Orbit calculations are more difficult for high-current beams. In this case, the space-charge of the beam can contribute to electric fields in the propagation region and affect the distribution
of image charge on surrounding electrodes. For this reason, Trak has the capability to update the electrostatic field using information on the space-charge density associated with the particle flow. This procedure is called a self-consistent orbit calculation. A beam is represented by a collection of model particles, each carrying a fraction of the beam current, $\delta I$. At each time step $\delta t$, the space-charge of the element occupied by a ray is augmented by an amount $\delta I \delta t$. Trak then recalculates the electric field with the extra space-charge. The problem with this approach is that the final orbits of the particles need not be the same as those used to calculate the space-charge. The resolution is to iterate for several cycles using suitable space-charge averaging. This procedure usually converges to the correct solution, even for intense beams.

High-current charged-particle beams have little effect on solenoid-type magnetic fields ( $B_{z}$ and $B_{r}$ in cylindrical problems, $B_{x}$ and $B_{y}$ in planar geometry). Therefore, Trak does not modify the applied magnetic field solution. On the other hand, relativistic beams generate magnetic field components $B_{\theta}$ (cylindrical) or $B_{z}$ (rectangular) that may strongly influence particle dynamics. To address this problem, Trak has the capability to find spatial variations of beam current and beam-generated magnetic fields that are recorded on the electric-field mesh (RelBeam tracking mode).

### 1.5 Tracking mode

A Trak calculation is performed in one of the following six calculation modes:

- TRACK. Single-particle tracking in applied electric and magnetic fields with no beamgenerated components. Particles may be generated from a user-specified list or automatically along an emission surface on a region boundary. Application to low-current or neutralized beams.
- FLINE. Tracing field lines in an electrostatic solution from EStat. A common application is computation of charged-particle flow lines in a resistive medium.
- SCHARGE Non-relativistic high-current electron and/or ion beams with self-consistent space-charge effects. Particle generation from a user-specified list and/or Child-law emission surfaces.
- RELBEAM Relativistic high-current electron and/or ion beams with self-consistent effects of beam-generated electric and magnetic fields. Particle generation from a user-specified list and/or Child-law emission surfaces.
- FEMIT Electron field emission with self-consistent beam-generated fields. Particle generation from a user-specified list and/or an emission surface that follows the FowlerNordheim equation. Applications to vacuum microelectronics.
- PLASMA High-current ion beam generation from free plasma surfaces, Particle generation from a user-specified list and/or Child-law emission surfaces. The shape of the emission surface is automatically corrected to ensure uniform ion flux.


Figure 2: Region definitions for the KLYSTRONGUN example. Dimensions in inches.

## 2 Application example

### 2.1 Setup

In this chapter we shall step through a Trak application. The calculation determines the performance of a high-intensity, relativistic klystron gun. The gun is designed for strong beam convergence and therefore represents a challenge to the accuracy of a numerical code. Figure 2 shows the geometry, a figure of revolution about the $z$ axis along the bottom. An electron beam of current 460 A is extracted from a spherical-section cathode across a 660 kV acceleration gap. The simulations involve only an applied electric field - we could add a magnetic field to investigate beam matching into a solenoid.

We shall use the following programs: tc.exe, mesh.exe, estat.exe and trak.exe. Make sure that you have created a data directory such as \tricomp $\backslash$ buffer and the tc.exe has the correct settings for the program and data directory. Move the file KLYSTRONGUN.MIN to the data directory.

### 2.2 Defining the geometry

We shall work from an existing Mesh input script. Run Mesh, click on the command File/Load.Script (MIN) and choose the file KLYSTRONGUN .MIN. Pick the command Edit script/Graphics to enter the drawing editor. Here, you can view the geometry and confirm the region assignments. Click the Foundation display command. Note the fine mesh resolution near the axis for a good representation of electric fields within the converged beam. Figure 3 shows a detail of


Figure 3: Detail of the mesh on the axis near the cathode for the KLYSTRONGUN example showing node identities.
the mesh at the axis near the cathode. The main difference from a standard input mesh for EStat is the presence of Region 6, an open region that covers the surface of the cathode (nodes marked in red in Fig. 3). The associated nodes have the same potential as those of the cathode (Region 3); therefore, they do not affect the electrostatic solution. The marked nodes are used in Trak to identify surface facets that will act as emission sites for electrons.

Abandon the drawing to return to the main menu. Click the Process command to create the mesh. You can use the plot functions of Mesh to inspect the completed conformal mesh. Be sure to click the Save mesh (MOU) command to create the file KLYSTRONGUN.mOU.

### 2.3 Generating the applied field

The first task to create an input electrostatic solution is define control parameters and material properties. Run EStat and choose the Setup command. Choose the file KLYSTRONGUn.mou. The program displays the dialog of Fig. 4. Fill in the values as shown. In the Control parameter group, we accept most of the defaults. The geometry is set to Cylindrical and the unit conversion parameter is set to $D U n i t=39.37$ inches $/$ meter. The material properties in the grid are simple. Region 1 (vacuum) is a dielectric with $\epsilon_{r}=1.0$. Regions 2 (anode) and 5 (vacuum chamber) are at ground potential, while the electrode regions of the cathode assembly (Region 3, 4 and 6 ) are at -660.0 kV . Click $O K$ and accept the default name to create the file KLYSTRONGUN.EIN.

Choose the Solve command. EStat takes a few seconds to find the electrostatic solution and saves the file KLYSTRONGUN.EOU. You can use the plot functions of EStat to investigate the solution. Later, Trak will create another electrostatic solution file, KLYSTRONGUNP.EOU, that includes the effects of the beam space charge.

### 2.4 Creating the Trak control script

We can now turn to the main task of generating a beam solution. Run Trak and pick the Setup command. The dialog gives a choice of run mode. Electrons with 660.0 keV kinetic


Figure 4: Setting parameters for the EStat solution - KLYSTRONGUN example.
energy have a relativistic energy factor $\gamma=2.29$, significantly larger than unity. Therefore, beam-generated magnetic fields play a significant role and we must choose the RelBeam option in the initial dialog. After you click OK, the program displays the setup dialog of Fig. 5. Fill in the values as shown. In the Fields section we specify that the program should load mesh and initial electric field information from KLYSTRONGUN.EOU. The parameters MaxCycle and ResTarget control recalculation of the electric field with the addition of beam space charge. Spatial quantities appearing the script should be scaled by a factor $(39.37)^{-1}$ to convert them to meters. In the Particles section we specify two parameters to control the self-consistent solution. There are 20 cycles of orbit tracking and field recalculation with a charge-averaging factor $A v g=0.20$. Electrons will be generated along an emission surface of facets connecting the nodes of Region 6. The parameters in the Emission section have the following meanings: 1) Mass $=0.0$ (insert the electron mass in AMU), 2) Charge $=-1.0$ (use the electron charge) and DEmit $=0.07$ (position the Child-law calculation surface about 2.8 element widths from the physical cathode surface). Section 10.3 describes emission surface parameters in detail. Finally, entries in the Diagnostics specify that the code should create a file KLYSTRONGUNP.PRT containing particle parameters at the system exit and a file KLYSTRONGUNP.EOU that describes the modified electric field. Click Write script and save the file in the working directory with the name KLYSTRONGUN. TIN.

### 2.5 Running Trak and plotting orbits

Pick the command Solve in the Trak main menu and choose the input file KLYSTRONGUN.TIN. The blue color of the screen indicates that the program is in the solution mode. The status bar at the bottom reports progress. For each of 20 main cycles, Trak computes orbits of 216 model particles, corrects the space charge and then performs an iterative matrix solution to find the modified electrostatic potential. On the final cycle, the program creates the PRT and EOU files


Figure 5: Setting parameters for the Trak solution - KLYSTRONGUN example.
requested as well as a record of orbit vectors in the plot file KLYSTRONGUN.TOU.
Pick the Plot command to enter the plot menu and click on File/Load electric field. In the dialog choose KLYSTRONGUN.EOU. The program reads the file and creates a default plot of equipotential contours. In comparison to the applied-field solution, note that the electric field amplitude over the cathode surface has been reduced to approximately zero by the Child-law emission process. Next, pick Load/Orbits and choose KLYSTRONGUN.TOU. The program superimposes the orbits on the boundary and field information. At this point, you can experiment with options in the plot menu. Section 5.2 gives a detailed description of available functions. The plot of Fig. 1 was created by choosing the Element field plot type and $|\mathbf{E}|$ as the plotted quantity. To differentiate orbits, the parameter NSkip in the Orbit filters dialog was set to 3.

The Trak listing file contains a wealth of information for understanding a run or debugging problems. Return to the main menu, pick the command File/Edit listing (TLS) and choose KLYSTRONGUN.TLS. Move to the end of the file. Following an extended table of final particle parameters, there is a listing of total emitted current as a function of cycle number (Table 2). This information is useful to check if the choices of the number of cycles and the charge-averaging parameter were correct to ensure solution convergence. With proper averaging, Trak converges to a solution where the particle orbits and consequent space-charge density are consistent with the total electric field.

### 2.6 Modifying the script for advanced dialognostics

Trak has an extensive set of special features. It would be unwieldy, if not impossible, to include all of them in the script generation dialogs (Fig. 5). In this section, we shall add commands to the script we have prepared to invoke two special functions: 1) calculation of beam current density as a function of radius at several axial positions and 2) generation of a file contain

Table 2: Current convergence history - KLYSTRONGUN example.

| NCycle | Total emitted <br> current (A) |
| :---: | :---: |
| $========================$ |  |
| 1 | $5.1091 \mathrm{E}+02$ |
| 2 | $5.1802 \mathrm{E}+02$ |
| 3 | $7.3695 \mathrm{E}+02$ |
| 4 | $8.6296 \mathrm{E}+02$ |
| 5 | $8.3152 \mathrm{E}+02$ |
| 6 | $5.9833 \mathrm{E}+02$ |
| $\ldots$ |  |
| 14 | $4.7854 \mathrm{E}+02$ |
| 15 | $4.7855 \mathrm{E}+02$ |
| 16 | $4.7860 \mathrm{E}+02$ |
| 17 | $4.7867 \mathrm{E}+02$ |
| 18 | $4.7873 \mathrm{E}+02$ |
| 19 | $4.7876 \mathrm{E}+02$ |
| 20 | $4.7887 \mathrm{E}+02$ |

information on the spatial distribution of beam-generated magnetic field.
In the main Trak menu, pick the command File/Edit script (TIN) and choose KLYSTRONGUN.TIN. The file is loaded in a full-featured Windows editor. Modify the Diagnostics section of the script so that it looks like Table 3. The CDens commands instruct the program to calculate the beam current density through planes normal to the $z$ axis at several distances from the cathode. The $B B D u m p$ command saves information on the toroidal magnetic field.

In response to the CDens command, Trak uses information stored on the beam-magneticfield mesh to add tables to the listing file. Figure 6 shows a plot of the radial current distribution of the converging beam. Note how nonlinear focusing fields on the beam envelope have produced a local enhancement of current density. The file KLYSTRONGUNP. BBD can be loaded into Trak with the Load beam magnetic field command of the plot menu. Boundaries and values of $\left|\mathbf{B}_{\theta}\right|$ can be included in orbit plots.

Table 3: Modified diagnostic section - KLYSTRONGUN example.

```
DIAGNOSTICS
    PARTFILE: klystrongunp
    EDUMP: klystrongunp
    PARTLIST
* Add these lines
    CDens 1.0 1.2 30
    CDens 2.0 0.8 20
    CDens 3.0 0.6 16
    CDens 4.0 0.4 12
    CDens 5.0 0.3 10
    BBDump KLYSTRONGUNP
END
```



Figure 6: Radial distribution of beam current density at several distances from the cathode KLYSTRONGUN example.

## 3 Interactive run setup

### 3.1 Structure of the Trak script

A control script FPREFIX.TIN is required for each Trak run. This chapter discusses how to create scripts using the interactive dialogs that appear in response to the $\operatorname{SetUp}$ command in the main Trak menu. Following chapters give detailed information on building scripts and adding features with a text editor.

Whichever method is used, it is useful to understand the script format. A script has three sections: Fields, Particles and Diagnostics. The file has the following structure:

```
Fields
    (Field commands)
End
Particles RunMode
    (Particle commands)
End
Diagnostics
    (Diagnostic commands)
End
EndFile
```

The sections must appear in the order shown and must terminate with an End command. Each section has a set of allowed commands. Within a section, valid commands may appear in any order. Trak begins processing a section when all commands have been read. The EndFile command closes all files and stops the program.

The commands in the Fields section control input of field solution files from EStat and/or PerMag. Advanced commands are available to adjust field values, introduce time variations, add constant magnetic field components and adjust the potential of individual electrodes.

The Particles section controls orbit computations. A string parameter in the section heading specifies the tracking mode (Sect. 1.5): Field, Track, SCharge, RelBeam, FEmit or Plasma. The valid commands of the Particles section depend on the tracking mode - the program stops with an error message if it finds an invalid command. The commands of the Particles section serve three functions:

- Controlling orbit calculations (global boundaries, mesh search options, time step, listing options, ...)
- Initiating particle orbits (particle parameters, marked emission surfaces, ...)
- Defining stopping criteria


Figure 7: Run setup dialog - Track mode.

Trak reads all commands in the Particles section, processes the information, and then computes the orbits. Depending on the tracking mode, the program may also update the potential and recalculate orbits over a number of cycles.

The commands of the Diagnostics section control special output listings of information on fields and calculated orbits. Trak can record scans of applied magnetic fields, self-consistent electric fields and beam-generated magnetic fields. The program makes formatted listings and output files of initial and final particle parameters. The program can perform automatic analyses of final beam distributions. You can also use GenDist for distribution calculations if the Trak run generates an output particle file.

### 3.2 Track mode

Trak features interactive dialogs to help you create basic run control scripts. To start, click the SetUp menu command or tool. In the initial dialog, pick the appropriate tracking mode. If you choose the default Track mode, the program calls up the dialog of Fig. 7. Note that dialog entries are divided into the same three categories as the Trak script: Fields, Particles and Diagnostics. Entries in the different dialog groups create commands in the corresponding script section. This chapter gives a brief description of the actions of the dialog entries. Detailed descriptions and commands to control advanced functions are described in Chaps. 6 through 15.

## EFILEPREFIX

The prefix of an EStat solution to provide electric field information for particle tracking.

## BFILEPREFIX

The prefix of a PerMag solution to provide magnetic field informations for particle tracking.

## DUNIT

A conversion factor for lengths that appear in Trak script commands, equal to the number of distance units per meter. For example, to supply dimensions in microns, set $D U n i t=1.0 \times 10^{6}$.

## PPREFIX IN

Supply the prefix of a file PPREFIX.PRT that contains a list of start parameters for particles. The format of the file is described in Sect. 8.2.

## DT

Supply a time step (in units of seconds) for orbit integrations. If the box is blank or contains 0.0, Trak will try to pick an appropriate value based on the properties of the mesh, the electric-field solution and the particle parameters.

The next four commands appear in the Emission surface group. An emission surface is an alternate way to initiate particle orbits. Trak identifies element facets of a fixed-potential region (electrode) and starts one or more particles per facet close to the surface in an adjacent dielectric element.

## REGNO

Supply the number of an emission line region on the surface of a fixed-potential region. Section 8.3 covers techniques to create emission surfaces in Mesh.

## MASS

Supply the mass of particles created on the emission surface in AMU (atomic mass units). Trak inserts the mass of the electron if 0.0 appears in the box.

## CHARGE

Supply the charge of particles created on the emission surface in fundamental charge units. Here, protons have Charge $=+1.0$ and electrons have Charge $=-1.0$.

## NPERSEG

Enter the number of orbits to start per emission surface facet.

## PPREFIX OUT

Supply a name if you want Trak to write a file PPREFIX.PRT of final orbit parameters. The file may be used as input in a subsequent Trak run or ported to the Field Precision programs GenDist, OmniTrak and GamBet.


Figure 8: Run setup dialog - FLine mode.

### 3.3 Field line mode

If you choose the FLine mode, Trak displays the dialog of Fig. 8. Field line tracking applies only to electric fields because magnetic field-line plots can easily be created in PerMag. Hence, there is no BFileName entry in the Fields section.

## FFILE PREFIX

Supply the prefix of a file PREFIX.FLD that contains a list of start parameters for field lines. The format of the file is described in Sect. 9.1.

## DS

Field line integrals proceed in small spatial steps rather than time steps. Enter a value in units specified by DUnit. Trak will pick a default if the field is blank or equals 0.0.

Entries in the Emission surface group are similar to those of the Track mode dialog. The main difference is the absence of particle parameters and the presence of the following entry.

## POLARITY

For Positive polarity, the spatial integral proceeds along the direction of positive electric field.

### 3.4 Space-charge and relativistic beam modes

The dialog of Fig. 9 is displayed when you pick either the SCharge or RelBeam modes. In comparison to the dialog of the Track mode, there are two additional entries in the Fields group.

## MAXCYCLE

Particle orbits are computed and the electric field is recalculated over NCycle field/particle cycles to include the effect of beam space charge. The parameter MaxCycle is the maximum number of iterations in the matrix solution for the electrostatic potential. Higher values give more accuracy at the expense of longer run times. The value of MaxCycle should be high


Figure 9: Run setup dialog - SCharge and RelBeam modes.
enough to ensure convergence at the end of the run. A solution is convergent if the following conditions are satisfied:

- The current from emission surfaces changes little between field/particle cycles.
- The initial relative residual (average error in the electrostatic potential) has a low value $\left(\ll 1.0 \times 10^{-6}\right.$ ) entering the final particle/field cycle.


## RESTARGET

Set a value for the target relative residual in the matrix solution for the electrostatic potential. The quantity is a measure of the accuracy of the solution and should be small compared to unity. Trak exits the field recalculation routine it the number of interactions exceeds MaxCycle or if the residual is less than the target value. Choices of MaxCycle and ResTarget affect the solution accuracy versus the run time.

The Emission surface group in the Particles section has the following additional parameter.

## DEMIT

The quantity DEmit is the distance between the physical source surface (e.g., cathode surface) and a virtual emission surface required to model Child-law emission. Enter DEmit in units set by the current value of $D U$ nit. The virtual surface be close to the source source and follow its general contours. On the other hand, DEmit must be $\geq 1.5$ times the local element width to ensure accurate calculations of the electric field.


Figure 10: Run setup dialog - FEmit mode.

## EPREFIX OUT

Record the final electrostatic field solution with the effects of space-charge in a file with the name EPREFIX.EOU. The file may be inspected with EStat or loaded into Trak for a subsequent solution.

### 3.5 Field-emission mode

Figure 10 show the dialog to generate a script for the FEmit mode. The entries are identical to those of the SCharge/RelBeam dialog with the exception of those in the Emission surface group. Because the mode handles only electron field emission, the options Mass and Charge are not included.

## WORKFUNC

Enter the emission surface work function in units of eV.

## BETA

The quantity $\beta$ is a parameter to represent field enhancement by submicroscopic structure of the emission surface (e.g., a patch covered with carbon nanotubes). Trak calculates the local field amplitude $|\mathbf{E}|$ and uses the quantity $\beta|\mathbf{E}|$ in the Fowler-Nordheim equation to find the local electron current density.

### 3.6 Plasma mode

The optimizing calculation in the plasma mode is complex and may require adjustment of parameters to achieve good results. It is essential to read Chap. 13 to understand the actions


Figure 11: Run setup dialog - Plasma mode.
of entries. Many entries have identical function to those in the SCharge and RelBeam modes. This section gives a brief summary of quantities unique to the Plasma mode. The Plasma group contains the following entries:

## NSURFACE

The number of cycles of surface adjustment. The default is $N$ Surface $=3$.

## NCORRECT

The number of orbit-field recalculations to determine a stable solution for space-charge-limited flow per surface adjustment (default, NCorrect $=5$ ).

## NINIT

The number of initial orbit-field calculations before the first surface adjustment (default, NInit $=$ 12).

The Emission surface group contain one additional parameter:

## DGAP

The approximate total width of the acceleration gap in units set by the current value of $D U n i t$.

## 4 Running the Trak program

### 4.1 Interactive mode commands

Trak runs interactively in a window if you launch trak.exe from TC or run the program without a command-line parameter. In this mode, you can carry out a variety of activities and perform several solutions in a session. In the interactive mode, the program serves three main functions, corresponding to the tools " $1 ", " 2$ " and " 3 ":

1. Setup, preparation of control scripts.
2. Run, generation of orbit solutions.
3. Plot, creation of orbit/field plots.

Note that Trak can perform only one function at a time. If you want to carry out extended orbit solutions while you are writing scripts or making plots, then launch a second instance of trak.exe. There is no speed penalty if you have a dual-processor machine.

The main menu has five entries: File, Setup, Solve, Plot, Tools and Help. We discussed Setup options in Chap.3, while the next chapter covers plotting capabilities. The following commands appear in the File, Solve and Help popup menus:

## EDIT SCRIPT (TIN)

EDIT LISTING (TLS)

## EDIT FILE

The commands invoke the internal editor to inspect or to modify text input and output files. With the Edit script command you can work on files with names of the form FPREFIX.TIN, while the Edit listing command displays file of type FPREFIX.TLS. Choosing a file from an alternate directory does not change the working directory of the program.

## RUN

Pick an input file with a name of the form FPREFIX.TIN to start a solution. The working directory changes if you pick a file from an alternate directory. The run begins if all required files are available in the working directory. The screen color is blue during extended calculations and the program reports run progress in the status bar.

## STOP

This command terminates the run immediately. The program records information currently available and closes all files.

## TRAK MANUAL

Displays this document in your default PDF viewer. Note that trak.pdf must be in the same directory as trak.exe.


Figure 12: Utilities in the Tool menu. a) Circular-beam generator. b) Time-step calculator.

### 4.2 Tool menu

This menu contains helpful utilities for run preparation.

## CIRCBEAM GENERATOR

This command brings up the dialog of Fig. $12 a$ to create a PRT file describing a laminar, circular beam with uniform current density. The routine generates a set of NPart orbits uniformly spaced in $r$. The assigned current is proportional to $r$ to give a uniform current density. The average beam motion is directed along $z$. A non-zero value for the envelope angle gives a diverging or converging beam with additional momentum components in the $x$ direction. If the Mass equals zero, the program inserts the mass of the electron.

## TIME-STEP CALCULATOR

In response to this command, Trak displays the dialog of Fig. $12 b$ for estimating values to use in the $D t$ command. Enter a value for the minimum element size and choose the appropriate length unit. Enter the particle parameters including maximum kinetic energy. The Atomic number value is used only for the particle type Ions. When you click the Calculate button, the program displays an appropriate value for $D t$ in seconds.

### 4.3 Command-line operation

You can invoke the orbit solution function of Trak directly from the command prompt. This feature is useful for batch file operation where a sequence of calculations runs automatically in the background. To make a single Trak simulation in the background, go to the Command Prompt in Windows and log to the data directory that contains the required input files. For example, suppose the input files SWITCH.TOU and SWITCH.TIN are stored in $\backslash$ TRICOMP $\backslash$ BUFFER and that the program trak.exe is in the directory $\backslash$ TRICOMP. From $\backslash$ TRICOMP $\backslash$ BUFFER type

The program runs silently, writing detailed information in the listing file SWITCH.TLS and the plot file SWITCH.TOU.

The command mode is useful for autonomous operation under batch file control. As an example, suppose you have prepared the input files KINJECTOR.MIN, KINJECTOR.EIN and KINJECTOR.TIN. The following batch file will initiate a complete calculation:

ECHO OFF
ECHO Running KINJECTOR example
START .. \MESH.EXE KINJECTOR
START .. \ESTAT.EXE KINJECTOR
START .. \TRAK.EXE KINJECTOR
ECHO KINJECTOR runs complete


Figure 13: Working environment for creating orbit/field plots.

## 5 Creating orbit plots

In response to the Plot command in the main menu, Trak enters a mode to create displays of orbits and field quantities. The program loads the command menu, toolbar and status bar shown in Fig. 13. There are three popup menus: File, Plot control and Export plot. The Return command restores the main menu. The display area is divided into three sections: 1) main plot, 2) particle information area (upper right) and 3) field information area (lower right).

### 5.1 File menu commands

## LOAD ORBITS

To begin a plotting session, you must load data from either an orbit or field file. Use this command to load orbits. The dialog shows a list of files with names of the form FNAME.TOU. Changing directories in the dialog changes the working directory. In the absence of a field file, Trak picks boundaries for the initial plot based on extreme values of the orbit vectors.

## LOAD ELECTRIC FIELD

Load a file of boundary and electric field information with a name of the form FNAME.EOU. The
file could be output from EStat or one created by Trak using the EDump command. There are three points to note:

- When a field plot is loaded, the boundaries of the solution region are used for the default plot boundaries.
- The program cannot check whether the field corresponds to the orbits - you must ensure that the data files match.
- If you have applied a spatial shift to the electric field in the Trak run, the orbits will be inconsistent if load the input applied field. You must create a file of the modified electric field using the EDump command and load it for a valid superimposed plot.


## LOAD MAGNETIC FIELD

Load information from a file with a name of the form FNAME. POU generated by PerMag.

## LOAD BEAM MAGNETIC FIELD

Load a file with a name of the form FNAME.BBD generated by Trak in a RelBeam calculation in response to the BBDump command.

## CLOSE ORBIT FILE

Close the current orbit file in preparation for loading another one, keeping the current field plot active.

## CLOSE FIELD FILE

Close the current field file in preparation for loading another one, keeping the current orbit plot active.

## CLOSE ORBIT AND FIELD FILES

Close all currently-loaded orbit and/or field files in preparation for loading new data.

ORBIT FILE INFORMATION Display information about the current orbit file (Fig. 14). The data on the spatial limits and the range of particle parameters (mass, charge and current) may be useful for setting plot filters. Note that information on the mass and charge of individual particles is present in all TOU files created by Version 7.0, but is not included in data files created by earlier versions of Trak.

FIELD FILE INFORMATION Show information on the current electric, magnetic or beamgenerated magnetic field file.


Figure 14: Information on the currently-loaded orbit file displayed in a message box.

### 5.2 Plot control menu commands

## ORBIT PLOT TYPE

Using the $(x, y, z)$ coordinates recorded in the plot file, Trak can create the following twodimensional plots: $y$ versus $x, x$ versus $z, y$ versus $z$ and $r$ versus $z$. Depending on the field symmetry, different plot types may or may not contain useful information. Trak suppresses the field plot if it is inconsistent with the current orbit plot type. The default types are $x$ versus $y$ for planar calculations and $r$ versus $z$ for cylindrical.

## ORBIT FILTERS

This command calls up the dialog of Fig. 15 to set filters for plotting particle orbits. You can use filters to set a plot color or to suppress plotting for classes of particles. For example, if the Trak calculation involved a counterflow of electrons and ions, you could plot electrons in red and ions in blue by setting filters based on particle mass. As shown in Fig. 15, there are three filters with associated screen colors blue, red and green. When a new orbit file is loaded, the default settings are that Filter 1 is active and encompasses all particles, while Filter 2 and 3 are inactive. The filter status is displayed in the information window. Within a filter, the active status of the selection criteria depend on the information recorded in the TOU file. To activate a filter, check the Active box and supply information in the active criterion boxes. The inputquantity units are amperes or amperes $/ \mathrm{m}$ for current, AMU for mass and the fundamental electron charge $\left(e=1.60210 \times 10^{-19}\right)$. The boxes on the right-hand side of the dialog define additional selection criteria. The parameter NSkip can be adjusted to reduce the density of orbits in a plot for clarity. For example, when NSkip $=5$ Trak plots orbits $N=1,6,11, \ldots$. The number $N$ gives the order in which the orbit appears in the TOU file and output PRT files. Use the parameters NPlotMin and NPlotMax to limit the range of $N$.


Figure 15: Dialog to set filter criteria for the display of particle orbits.

## FIELD PLOT TYPE

The program supports the following plot types:

- Mesh. Element facets of the computational mesh.
- Region. Computational mesh with elements color-coded by region number.
- Contour. Lines that follow constant values of a computed quantity: electrostatic potential, vector potential or stream function or $B_{\theta}$. When a magnetic field has been loaded, the contours show lines of magnetic flux density B.
- Element. Elements of the solution space color-coded according to a computed quantity (such as the electric field magnitude)


## FIELD QUANTITY

This command affects only element plots. Available quantities are $\phi$ or $|\mathbf{E}|$ for electric field files, field lines or $|\mathbf{B}|$ for magnetic field files and and $B_{\theta}$ or enclosed current for beam-generated magnetic field files.

## PLOT LIMITS

Use this command to set limits for the field quantity or to restore automatically scaling in field plots.

## NUMBER OF CONTOURS

Change the number of lines in contour plots.

## GRID CONTROL

Open a dialog to control the display of grid lines. Here, you can activate or suppress grid display. Alternatively, you can use the Toggle grid tool. You can also set specific horizontal or vertical intervals or restore automatic intervals. In the latter case, Trak chooses grid spacing to correspond to easily recognized numbers (i.e., $0.01,0.02,0.05, \ldots$ ). The intervals are displayed in the information area the grid is active.

## ELEMENT OUTLINES

Use this command if you want to add the boundaries of elements to mesh, region and element plots. The feature may be useful to check whether the grid resolution is adequate in a Trak simulation. If you deactivate element outlines in a mesh-type plot, the program includes only outlines of region boundaries.

## XY MAGNIFICATIONS

By default, Trak generates plots at approximately true scale. (The exact scaling depends on the properties of your monitor and the proportions of the program window.) The program has an alternate plot mode that is useful for charged-particle beam simulations where the solution size
in the transverse direction may be much smaller than the axial size. In the XY magnification mode, you can manually specify the coordinates of the plot boundaries. Trak adjusts scales so that the plot fills the full plot area. Note that the zoom and pan commands are inactive in the XY magnification mode.

## RESET PLOTS ON LOAD

In the default mode, Trak automatically resets plot parameters (current view, plot type, magnification mode,..) when you load new data with the commands of Sect. 5.1. Sometimes, you may want to compare a series of similar runs maintaining a specific view or magnification limits. In this case, use this command to deactivate autoscaling. The current setting (Autoset plot parameters or Fixed plot parameters) is shown on the right-hand side of the status bar. Note that Trak automatically rescales the plot when you switch from Fixed to Autoset mode.

## SAVE CURRENT PLOT

This command (which appears in the Export plot menu) is useful if you want to superimpose electric field, magnetic field and orbit information in the same plot or if you want to make a plot that shows small differences between orbit solutions. When you click on the command, Trak creates a bitmap image of the current plot. In the dialog, supply a file prefix. The plot will be stored in standard Portable Network Graphics format with the name FPREFIX.PNG. You can then superimpose this image on subsequent plots.

## COMBINE PLOTS

Combine the current plot with a stored bitmap image (or any PNG image) using the bitwise AND operation. The dialog displays a list of files with suffix PNG.

## UNDO COMBINATION

Reverse the image combination and restore the plot.
As an example, you might load a large volume magnetic field solution, set the plot limits to correspond to an electric field solution and then save the bitmap. You could then load orbit trajectories and the electric field solution to create a new plot. Finally, use the Combine plots command to include magnetic field lines. Figure 16 shows an example. Here are some rules for using bitmap superposition:

- For an accurate superposition, you must ensure that the current plot and the bitmap plot have the same spatial limits.
- The superposition looks best if one of the plots contains discrete line data (e.g., contour lines or particle orbits). Combining two element plots would give unpredictable results.
- For the best appearance, do not resize the program window between recording and combining operations. If the window has been resized, Trak will make its best effort to stretch the bitmap to fit.


Figure 16: Plot combining particle orbits, electrostatic equipotential lines, magnetic field lines and region boundaries in both field solutions.

- The Plot file commands in the Export menu use vector operations to reconstruct the current plot and will not include the combined information. To save the combined plot, use the Save current plot command.


## CONTOUR PLOT STYLE

Choose the method for displaying electrostatic contours or magnetic field lines. There are four choices: monochrome, monochrome with labels, colored and colored with labels. In the colored mode, the lines are color-coded according to the value of the plotted quantity. A legend is included in the information window to the right of the plot. In the labeled modes, contour lines are numbered according to their values. Overlapping labels on closely-spaced lines may look better in a zoomed view.

## SETTINGS/MOUSE/KEYBOARD <br> SETTINGS/SNAP MODE <br> SNAP DISTANCE <br> ZOOM WINDOW <br> ZOOM IN <br> EXPAND VIEW <br> GLOBAL VIEW <br> PAN VIEW <br> DEFAULT PRINTER <br> SAVE PLOT FILE <br> COPY TO CLIPBOARD

These commands adjust the plot view and send plots to printers and graphics files. Their functions are described in the EStat and PerMag manuals.


Figure 17: Distribution plot menu showing a phase space plot for an annular beam.

### 5.3 Distribution plot menu

In the Distribution menu, you can investigate the evolution of beam distributions as a function of position along the $x$ (planar) or $z$ (cylindrical) axis. There are two requirements to plot distributions:

- An orbit file (FNAME.TOU) must be loaded.
- Particle motion should be paraxial about $x$ or $z$.

The second item implies that the particles constitute a recognizable beam (i.e., orbits make small angles with respect to the axis).

When you enter the Distribution menu, Trak creates a default phase-space plot at a position along the axis approximately midway between the orbit starting and ending positions (Fig. 17). The plot shows the transverse displacements of particles from the axis ( $y$ or $r$ ) and the corresponding angle with respect the axis $\left(y^{\prime}\right.$ or $\left.r^{\prime}\right)$. The displacements are in the units set by the value of DUnit in the TOU file and the angles are in degrees. You can move in $x$ or $z$ with the following commands:

- Jump forward (double up-arrow tool): Move a large step in the $+x$ or $+z$ direction.
- Step forward (single up-arrow tool): Move a small step in the $+x$ or $+z$ direction.
- Step backward (single down-arrow tool): Move a small step in the $-x$ or $-z$ direction.
- Jump backward (double down-arrow tool): Move a large step in the $-x$ or $-z$ direction.

Alternatively, you can use the Set plane command to bring up a dialog. Here, you can move a slider to set an approximate position or type an exact value in the box.

In the default mode, Trak rescales graphs to fit the full plot area as you move. If you want to compare distributions, use the Plot limits command to set fixed values for the minimum and maximum values or displacement and/or angle. In the dialog, uncheck the Autoscale box and supply limits. The values computed for the plot may be exported to a text file. To activate the feature, click the command Toggle plot recording in the Export plot menu. Supply a prefix for a file with a name of the form FPREFIX.DPL (Distribution PLot). The values for subsequent graphs are recorded in the file. Click the command again to close the file and end recording. The following is a portion of the listing for the graph of Fig. 17:

```
Phase-space distribution, Z: 7.50750E+00
            r rp(deg)
============================
    5.28484E+00 1.14543E+00
    5.28728E+00 1.16563E+00
    5.28968E+00 1.19258E+00
```

Click on the Plot quantity command or tool to switch to a plot of current density as a function of $y$ or $r$. Depending on the number of available particles, Trak picks an optimum number of bins along $y$ or $r$ and assigns current using the cloud-in-cell method. Each particle has a transverse width $2 \Delta r$, where $\Delta r$ is the average spacing between particles. If a particle overlaps a bin, a portion of the particle current is assigned equal to the fraction of overlap. The procedure gives satisfactory results, even with a relatively small number of particles. The limitation is that variations of current over length scales less than $\Delta r$ cannot be resolved. Use more particles to improve the resolution. The Plot limits command is not active for currentdensity plots. To make comparisons, you can transfer information in the recording file to your own plot program. An example is shown below. The recorded quantities are the minimum, maximum and average transverse positions of the bin and current density in $\mathrm{A} / \mathrm{cm}^{2}$.

Current density calculation, Z: | $8.10690 \mathrm{E}+00$ |
| :---: |
| RIn |
| ROut |

$================================================$
RAvg

## 6 Electric field input and control

### 6.1 General commands

The first step processing a Trak script is to define electric and/or magnetic fields by reading solution files from EStat and/or PerMag. Commands that appear in the Fields section control this function. This chapter covers commands to load and to modify electric field solutions from EStat. Commands are displayed with symbolic parameters and also in the form they would appear in the script file.

## DUNIT DUnit <br> DUNIT $=39.37$

This command controls the interpretation of spatial coordinate input from script commands. The quantity DUnit (real) is the number of distance units per meter. For example, to enter positions in cm, set DUnit $=100.0$. The command can appear anywhere in the script and affects all following commands. Note that the values of DUnit defined in the EStat or PerMag input scripts set coordinates for the input meshes but have no effect on position quantities entered in the Trak script. The quantity DUnit is recorded in the TOU plot file and used to scale plot dimensions.

## BOUNDARY X1 Y1 X2 Y2 <br> BOUNDARY Z1 R1 Z2 R2 <br> BOUNDARY $=(0.0,0.0,20.0,5.0)$

Orbit calculations are performed inside a two-dimensional solution box with opposite corners defined by $\left(x_{1}, y_{1}\right)-\left(x_{2}, y_{2}\right)$ for planar solutions or $\left(z_{1}, r_{1}\right)-\left(z_{2}, r_{2}\right)$ for cylindrical geometry. Enter coordinates in units set by DUnit. Particle orbits terminate if they move outside the box. Trak interpolates the final orbit step so that the stopping point lies exactly on the box surface. If the Boundary command does not appear, Trak sets the solution volume as the largest box that overlaps the electrical and/or magnetic solutions. In the Track (single-particle) mode, the program sets the ballistic flag if the Boundary command is present. In this case, orbits continue even if they leave the boundaries of the electric and/or magnetic solution volume. The program takes $\mathbf{E}=0.0$ and $\mathbf{B}=0.0$ in regions that are inside the orbit calculation box but outside the field solution volumes. As an example, the ballistic mode is useful if you want to trace orbits to a focal point at a distance from a lens with localized field. Note that the ballistic mode may not be used in the SCharge and RelBeam modes because space-charge must be assigned along the full particle trajectory.

### 6.2 Loading and modifying EStat solutions

## EFILE FileName [EMult]

EFILE $=$ KlyGun.EOU
This command loads an electric field solution from EStat. The quantity FileName is the full name of the file (i.e,, EFTEST.EOU). The optional real-number parameter EMult is a global scaling factor. All values of electrostatic potential at nodes are multiplied by EMult when they are loaded into the program. This factor is useful if you want to investigate scaling with applied voltage without regenerating the EStat solution. The EStat file must be available in the working directory. The $z$ axis in the field solution corresponds to the $z$ axis for particle tracking in Trak. A solution with cylindrical symmetry has field components $E_{r}$ and $E_{z}$. The program determines $E_{x}$ and $E_{y}$ for tracking from $E_{r}$ from the particle position. A planar solution has field components $E_{x}$ and $E_{y}$ with $E_{z}=0.0$.

Note: In runs with both electric and magnetic fields, the field solutions must have the same symmetry - planar or cylindrical. In cylindrical simulations, both the electric and magnetic solutions must share the same $z$ axis.

## SHIFT E ZEShift <br> SHIFT(E) $=-5.67$

This command with the string parameter $E$ moves nodes in the electric field mesh along the $x$ direction (planar) or $z$ direction (cylindrical) according to

$$
\begin{equation*}
z_{\text {new }}=z_{\text {old }}+Z_{\text {eshift }} \tag{5}
\end{equation*}
$$

Enter the real-number parameter ZEShift in the current units set by the DUnit command. As an example, you could use this command to make small changes in the position of the electric solution relative to a magnetic solution to optimize beam matching to a magnetic focusing system. The command is also useful in simulations of particle motion through a periodic focusing system. Here, you can split the particle simulation into several stages with shifted field solutions.

## MODFUNC E TABLE FileName [Toff Tmult Foff Fmult] MODFUNC(E,TABLE) = StepFunc.WAV

You can use the form of the ModFunc command to add an arbitrary temporal modulation of electric fields. This capability may be applied only in the Track tracking mode. The keyword Table designates that a tabular function will be imported from a file. The quantity FileName is the full name of the file (available in the current directory). The file consists of data lines that define the time variation of a function.

Temporal tables have the format:

```
t1 fe(t1)
t2 fe(t2)
t3 fe(t3)
tn fe(tn)
ENDFILE
```

Values of $t$ should be in units of seconds and values of $f_{e}(t)$ may be in any relative units. The number of data lines should be less than or equal to 256 . If the optional real-number parameters Toff, Tmult, Foff and Fmult appear, values in the table are modified according to

$$
\begin{align*}
t_{\text {code }} & =T_{\text {mult }} f_{t a b}+T_{o f f}  \tag{6}\\
f_{\text {code }} & =F_{\text {mult }} f_{t a b}+F_{o f f} \tag{7}
\end{align*}
$$

The modulation file follows the standard rules for TriComp tabular functions. You can use any of the standard delimiters to separate quantities on the line including Space and Tab. Comment lines (beginning with an asterisk) may be included. Note that all particle orbits start from their initial position at $t=0.0$. Using the elapsed time $t$ of an orbit, the program applies a cubic spline interpolation to find $f_{e}(t)$. The table values should define a smooth function with continuous first derivatives. All electric field components are then multiplied by $f_{e}(t)$.

By default, Trak interprets the table as a periodic function. If the elapsed time of an orbit exceeds the maximum time on the table, Trak returns to the beginning. To illustrate, if the orbit time is $t=5.0 \mathrm{~ns}$ and if the maximum time value in the table is $t_{\max }=4.0 \mathrm{~ns}$, then $f_{e}$ is evaluated at 1.0 ns . If you want to apply a single electric-field pulse with zero fields thereafter, be sure that the final entry in the table is of the form

```
tmax 0.0
```

where $t_{\text {max }}$ is larger than the longest particle transit time.

## MODFUNC E $>$ Function <br> $\operatorname{MODFUNC}(E)>10.0+\cos (3.1416 * \$ t / 25.6)$

Define a modulation function for electric field values from a mathematical expression. The symbol $>$ designates that a function string occupies the remainder of the line. The function may be up to 230 characters in length and follows the format described below. The function defines a variation in time, $f(t)$. The parser uses the Perl standard for the time variable: $\$ t$ stands for $t$.

Trak incorporates a flexible and robust algebraic function interpreter. A function is a string (up to 230 characters) that may include the following entities:

- The time variable \$t.
- Real and/or integer numbers in any valid format (e.g., 3.1415, 476, 1.367E23, 6.25E-02, $8.92 \mathrm{E}+04, \ldots$ ). Integers are converted to real numbers for evaluation.
- Binary operations: + (addition), - (subtraction), * (multiplication), / (division) and $\wedge$ (exponentiation).
- Functions: abs (absolute value), $\sin$ (sine), cos (cosine), tan (tangent), In (normal logarithm), log (base 10 logorithm), exp (normal exponent) and sqt (square root).
- Up to 20 sets of parentheses to any depth.
- Any number of space delimiters.

The parser conforms to the standard algebraic rules and features comprehensive error checking. Errors may include unbalanced parentheses, unrecognized characters and sequential binary operations. To illustrate a valid example, the expression

```
1 - exp(-1.0*(($t^2)/24))
```

corresponds to

$$
\begin{equation*}
1-\exp \left[-\left(\frac{t^{2}}{24}\right)\right] \tag{8}
\end{equation*}
$$

## CHANGEPOT RegNo PotNew CHANGEPOT(6) $=25000.0$

This command can be used to change the potential of a individual electrode. The quantity RegNo (integer) corresponds to the region number defined in Mesh. The region must have the fixed-potential property. The quantity PotNew (real) is the new value of potential (in volts). You can include multiple ChangePot commands in the file. After all electrode values are set, the program performs a relaxation operation to correct values of potential at intervening variable points.

Note: If you modify the electric field solution with the EMult parameter, Shift command or ChangePot command, be careful when creating plots. If you load the original applied field, the field display will not correspond to fields used to compute the particle orbits. Use the EDump command in the Diagnostics section to make a record of the modified electric field.

### 6.3 Controlling electric field recalculation

The following commands control the iterative procedure used to update the electric field solution. Updates are required if the ChangePot command appears or if effects of beam space charge must be included (SCharge, RelBeam, FEmit and Plasma tracking modes).

## MAXCYCLE MaxCy <br> MAXCYCLE $=2500$

The integer quantity MaxCycle is the maximum number of iteration cycles in the matrix solution for the field. Larger values usually give higher accuracy. The default values are MaxCycle $=$ 2500 for initial adjustments in response to the ChangePot command and MaxCycle $=250$ for field relaxations on each tracking cycle in the SCharge, RelBeam, FEmit and Plasma tracking modes

## OMEGA Omega <br> OMEGA $=1.95$

The quantity Omega is the successive over-relaxation factor for the electric field solution. Assign a value in the range 0.0 to 2.0. Values close to 2.0 usually give faster convergence. Lower the parameter if the solution fails to converge. If the Omega command does not appear, Trak uses default values determined by the Chebyshev prescription.

## RESTARGET = ResTarget <br> RESTARGET $=1.0 \mathrm{E}-8$

The residual is the relative error in the electric field solution and should approach a small value compared to unity. The electric field relaxation terminates if the residual falls below the quantity ResTarget (real) or if the number of relaxation cycles exceeds MaxCy. The default value is ResTarget $=1.0 \times 10^{-7}$.

## $7 \quad$ Magnetic field input and control

### 7.1 Loading PerMag solutions

The commands to load and to modify magnetic field solutions created by PerMag are similar to those used for electric field files.

## BFILE: FileName [BMult] <br> BFILE $=$ MLENS.POU (1.4)

This command loads a magnetic field solution created with PerMag. The quantity FileName is the full name of the file (i.e.,SOLENOID.POU). The optional real-number parameter BMult is a global field scaling factor. Values of vector potential at all nodes are multiplied by BMult when they are loaded into the program. This factor is useful if you want to investigate scaling with applied magnetic field without regenerating the PerMag solution. The solution file must be available in the working directory. The $z$ axis in the field solution corresponds to the $z$ axis for particle tracking. A solution with cylindrical symmetry has non-zero field components $B_{z}$ and $B_{r}$, while the components from a planar solution are $B_{x}$ and $B_{y}$.

## SHIFT B ZBShift <br> $\operatorname{SHIFT}(B)=0.05$

The Shift command with the key symbol B moves nodes in the magnetic field mesh along the $x$ direction (planar) or $z$ direction. Enter the real-number parameter ZBShift in the units set by the DUnit command.

```
MODFUNC B TABLE FileName MODFUNC(B,TABLE) \(=\) SlowRise.PLS
MODFUNC B > Function
MODFUNC \((\mathrm{B})>0.566+\sin ((\$ t+5.0 \mathrm{E}-8) / 1.2 \mathrm{E}-7)\)
```

The ModFunc command with the key symbol $B$ adds time variations to magnetic fields. Modulation functions were described in Sect. 6.2. The capability may be applied only in the Track tracking mode.

You should note the following facts about time variations of magnetic fields:

- The modulation function is applied to the total magnetic field calculated from all sources.
- Trak simply multiplies static field values by the modulation function and makes no checks that the resulting time-dependent fields approximate a solution to Maxwell's equations. You must ensure that the field values are physically valid.

Table 4: Example of a tabular listing of $B_{z}(0, z)$

* Table from SOL_LENS.BOU
* z Bz
* =======================

SYMMETRY: Cylin
$-9.000 \mathrm{E}+00 \quad 4.421 \mathrm{E}-06$
$-8.852 \mathrm{E}+00 \quad 5.926 \mathrm{E}-05$
$-8.703 \mathrm{E}+00 \quad 1.173 \mathrm{E}-04$
$-8.555 \mathrm{E}+00 \quad 1.780 \mathrm{E}-04$

| $9.258 \mathrm{E}+00$ | $1.014 \mathrm{E}-04$ |
| :--- | :--- |
| $9.406 \mathrm{E}+00$ | $7.838 \mathrm{E}-05$ |
| $9.555 \mathrm{E}+00$ | $5.670 \mathrm{E}-05$ |
| $9.703 \mathrm{E}+00$ | $3.685 \mathrm{E}-05$ |
| $9.852 \mathrm{E}+00$ | $1.767 \mathrm{E}-05$ |
| $1.000 \mathrm{E}+01$ | $7.111 \mathrm{E}-11$ |
| E |  |

### 7.2 Alternate magnetic field sources

In contrast to electric fields, Trak can combine several sources of magnetic fields. The field components are additive when multiple sources are defined.

## BTABLE $=$ FileName Zoff Zmult Boff Bmult BTABLE $=$ Bucking.DAT (2.0, 1.0, 0.0, 300.0)

Trak can derive fields from expansions based on a table of values of the on-axis magnetic field in both planar and cylindrical geometries. The string parameter FileName is the full name of a file with the formal described below. Optionally, you may supply four real numbers as parameters in the command: Zoff, ZMult, Boff and Bmult. The parameters modify table values entered in the program according to

$$
\begin{array}{r}
z_{\text {prog }}=Z_{\text {mult }} z_{\text {tab }}+Z_{o f f}, \\
B_{z \text { prog }}=B_{\text {mult }} B_{z t a b}+B_{o f f} . \tag{10}
\end{array}
$$

Table 4 shows an example of a magnetic table. The table may contain comment lines, data lines, an EndFile command and a Symmetry command. The Symmetry command must be the first non-comment line in the file and has the parameters Cylin or Rect. In the Cylin option, the data lines contain values of $z$ and $B_{z}(0, z)$. In the Rect option enter $x$ and $B_{x}(0, x)$. The adjusted values of $z$ should be in the current spatial units defined by DUnit and $B_{z}(0, z)$ should be in tesla. The file may contain up to 256 data and must terminate with the EndFile command.

Note: Trak uses cubic spline interpolation to analyze the on-axis magnetic field. The method supplies only first and second derivatives. Therefore, the quantities $B_{r}(r, z)$ and $B_{y}(y, x)$ vary
linearly in $r$ or $y$. You must use a finite-element magnetic field solution to investigate effects of non-linear field variations.

## BUNI $=\mathrm{Bx0}$ By0 Bz0 <br> BUNI $=(0.25 \mathrm{E}-40.00 .0)$

This command defines spatially-uniform magnetic field components. The feature could be used, for example, to simulate the effects of the earth's magnetic field on an electro-optical device. Enter magnetic field values in tesla. Note that uniform field components may be used only in the Track tracking mode.

## BTHETA AxisCurr RWire <br> BTHETA $=1200.0$ (0.001)

This command adds a toroidal magnetic field generated by an on-axis wire. One application of the feature is modeling wire transport of an intense electron beam. The field is uniform in $z$. The quantity AxisCurr is the wire current in amperes. Use a negative value for a current in the $-z$ direction. The quantity $R$ Wire is the wire radius in units defined by DUnit. The wire radius does not affect the field calculation. It is used to estimate particle losses on the wire. An orbit stops if it reaches a radius less than RWire.

## 8 Single-particle tracking

### 8.1 Command functions in the Track mode

In this chapter we proceed to commands that may appear in the Particles section of the input script under the Track mode:

## PARTICLES TRACK

...
(Commands)

## END

In this mode Trak calculates orbits in the single-particle limit. The term implies that the fields created by the particles are negligible compared to the applied fields (i.e., low-current beams). In this case, each particle can be treated independently and the calculation of orbits is a straightforward process. Allowed commands in the Particles Track section serve five functions:

- Set starting points for particle orbits.
- Control orbit integrations.
- Define region material properties relevant to orbit tracking.
- Set conditions for orbit stopping.
- Control diagnostic listings that can be generated during orbit integrations.

Many of the commands in the last four categories appear in all particle and field-line tracking modes.

### 8.2 Starting particles from a list

The simplest way to start particles in the Track mode is through list input. Here you specify the species, kinetic energy, start position and direction of from 1 to 20000 particles. Two commands are used for list input:

## PLIST

This command signals that a list of particle starting parameters follows in the control script.
The following example illustrates a standard particle list:

## PLIST

| * | Mass | Chrg | Eng | x | y | z | px | py | pz |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0.0 | -1.0 | 0.7399 E 6 | 0.1 | 0.0 | -8.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 0.2 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | $0.7399 E 6$ | 0.3 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | $0.7399 E 6$ | 0.4 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 0.5 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | $0.7399 E 6$ | 0.6 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | $0.7399 E 6$ | 0.7 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 0.8 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 0.9 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 1.0 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | $0.7399 E 6$ | 1.1 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 1.2 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 1.3 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | 0.7399 E 6 | 1.4 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
|  | 0.0 | -1.0 | $0.7399 E 6$ | 1.5 | 0.0 | -9.0 | 0.00 | 0.00 | 1.00 |
| E |  |  |  |  |  |  |  |  |  |

The maximum number of lines is 20000 . Comment lines (starting with an asterisk) may be included. Each data line contains nine real numbers to represent the following quantities:

- Mass. The particle mass in AMU (one atomic mass unit corresponds to $1.660538782 \times$ $10^{-27} \mathrm{~kg}$ ). An entry of 1.0073 designates a proton. If 0.0 appears in the column, the program inserts the value for an electron. A run in the Track mode may contain particles with different values of Mass and Charge.
- Charge. The particle charge in units of e ( $1.60210 \times 10^{-19}$ coulomb). An ion has charge +1.0 and an electron has charge -1.0.
- Energy. The initial particle energy in eV ( 1 electron volt $=1.60210 \times 10^{-19}$ joules).
- Position. The particle position $(x, y, z)$ in units set by the current value of $D U n i t$.
- Direction. Normalized momentum fractions $\left(u_{x}, u_{y}, u_{z}\right)$ that give the direction of particle motion. Here, $u_{x}=p_{x} / p_{\text {total }}$. Trak will normalize the numbers; therefore, the sum of the squares of the components need not equal to unity. To represent an initially-stationary particle, set Energy $=0.0$ and $u_{x}=u_{y}=u_{z}=1.0$.

The list must terminate with an End command.

## PFILE $=$ FPrefix

PFILE $=$ Run01
Trak can read particle starting point information from a text file rather than from the control script. The parameter FPrefix is the prefix of a file with a name of the form FPREFIX.PRT in the current directory. The file contains from 1 to 20000 particle data lines in the format described above terminated by an End command. Lines may incorporate any of the standard

TriComp delimiters including spaces and tabs. The file may include comment lines (beginning with an asterisk) and text in any formal after the End command.

You can prepare standard particle files (FPrefix.PRT) with text editors, spreadsheets or your own programs. Output PRT files from Trak may be used as input to a subsequent run. Files of high-energy electrons may be transferred to the GamBet Monte Carlo code. It is also possible to generate files automatically to represent a variety of distributions using the GenDist utility program. GenDist can also read PRT files created by Trak to generate statistical analysis and distribution plots. Finally, you can use GenDist to filter distributions to remove unwanted particles.

### 8.3 Starting particles from an emission surface

Emission surfaces are critical to the operation of Trak in the SCharge, RelBeam, FEmit and Plasma tracking modes. Emission surfaces are useful in the Track mode for a specific application: generation of a distribution of particles with zero kinetic energy from electrodes or surfaces of arbitrary shape. Emission surfaces can be employed only in calculations that include an electric field. In a pure magnetic field, particles with zero kinetic energy would simply remain at the same position.

This section addresses the following questions:

- What is an emission surface?
- How do you create an emission surface in Mesh?
- How does Trak identify an emission surface and generate particles?
- How can you control emission surfaces through Trak commands?

An emission surface is simply a contiguous line region in the electric field mesh. To review, in the Mesh program a line region is one that does not have the Fill keyword in the Region command. In this case Mesh assigns the region number to nodes along the lines and arcs that constitute the boundary, but the program does not change the identity of bordering elements (Fig. 18). A line region need not outline a closed volume. In the SCharge, RelBeam and FEmit modes, the line region must be on the surface of a fixed-potential filled region so that Trak can apply the correct emission physics. We can envision that the line region paints a portion of the electrode surface to define the area of emission. Emission surfaces are more flexible in the Track mode - the line region may be on the surface of an electrode or within the volumes of dielectric and vacuum regions. If the line region is on the surface of an electrode, set it to the fixed-potential condition in EStat and assign the same potential as the electrode. With these settings the presence of the emission surface will not perturb the electric field solution. Similarly, a line region in a dielectric volume should be assigned the same value of relative dielectric constant $\epsilon_{r}$.

If region number NReg is defined as an emission region, Trak searches the mesh and collects all nodes with that number. The program then creates a list of emission facets: element sides that connect two emission nodes (Fig. 18). Trak attempts to place the facets in a logical connected order starting from the node nearest the axis and then checks that the facets form a


Figure 18: Definition of an emission surface on a conformal triangular mesh.
contiguous set. If we specify that one particle should be created per segment, the code finds the midpoint of each facet. If the facet has dielectric elements on both sides (i.e., the electric field at the midpoint is non-zero), the location is used as the starting point for the particle orbit. If one element has the fixed-potential condition, the code moves the emission point slightly into the dielectric element for a valid field interpolation. Trak issues an error message if both elements adjacent to an emission facet are part of a fixed-potential region. To create multiple particles per facet, the code first divides each facet into a number of segments and then starts particles from the midpoints of the segments. Emission surfaces can have arbitrary shape; therefore, emission points may not be uniformly spaced.

The following commands control emission surfaces in the Track mode.

## EMIT NReg Mass Charge NPerSeg

$\operatorname{EMIT}(5)=(0.0,-1.0,3)$
This command states that nodes with region number NReg constitute an emission surface. The real number parameters Mass and Charge give the mass and charge of the particles that will be created. Enter the mass in AMU. If 0.0 appears in the column, the program inserts the value for an electron. The quantity Charge is the particle charge in units of fundamental charge. An ion has charge +1.0 and an electron has charge -1.0. Note that only one particle species can be created on an emission surface. You can define several emission surfaces in a run, each with a different particle species. The final integer parameter, NPerSeg, is the number of segments per facet. For example, the choice $N$ PerSeg $=3$ instructs the code to create three particle orbits per facet.

## START NReg XStart YStart <br> START NReg ZStart RStart

START(5) $=(0.0,5.0)$
In processing an emission surface Trak must start with a node at the end of the line region to arrange the facets properly. Sometimes the end point may not be the point closest to the axis, or there may be an ambiguity (such as a horizontal line). The code issues an error message if facet ordering fails. You can correct the problem by actively setting the endpoint of the line region. The integer parameter NReg is the region number of surface. Enter the coordinates of a point close to the end in units set by the current value of DUnit. To fix problems, note that Trak records information on the selection of facets and the ordering procedure in the listing file FPrefix.TLS.

### 8.4 Controlling orbit integrations

The following commands control the numerical solution of particle orbits.

## DT Dt <br> DT $=1.0 \mathrm{E}-12$

This command sets the integration time step (in seconds). Generally, the quantity $D t$ should be less than the minimum time it takes for a particle to cross an element. Lower values give higher accuracy but extend the run time. If the command does not appear, Trak makes a guess based on estimates of the minimum element size and maximum particle velocity. The velocity is determined by checking the initial kinetic energies and/or the maximum change in potential energy in the solution space. In solutions with a magnetic field, it is essential that the time step is much smaller than the gyration period:

$$
\begin{equation*}
\Delta t \ll \frac{2 \pi}{\omega_{g}}=\frac{2 \pi \gamma m_{0}}{q B} \tag{11}
\end{equation*}
$$

In Eq. $11, B$ is the maximum value of magnetic flux density. The particle has relativistic energy factor $\gamma$, charge $q$ and rest mass $m_{0}$. In solutions with strong magnetic fields, you should always set $D t$ manually, ensuring that it satisfies Eq. 11.

## DT DTRef MASS

## $\mathrm{DT}=2.3 \mathrm{E}-8$ (MASS)

This form of the $D t$ command includes the keyword Mass. The form must be used whenever a simulation contains particles with different masses. The quantity DtRef is a reference time step for particles with a mass of 1.0 AMU (atomic mass unit). The actual time step used for a particle orbit is given by

$$
\begin{equation*}
\Delta t=\frac{\Delta t_{r e f}}{\sqrt{m_{0}}} \tag{12}
\end{equation*}
$$

where $m_{0}$ is the particle rest mass in AMU. Therefore in a mixed simulation with protons and electrons the time step for electron orbits will be about $1 / 43$ of the time step used for the protons. As an example, consider the calculation of electron extraction and ion back-flow in a gun with 250 kV applied voltage. Suppose the minimum element size is 1.0 mm . The maximum
velocity of a proton would be $6.92 \times 10^{6} \mathrm{~m} / \mathrm{s}$. Therefore, we set $\Delta t_{\text {ref }}=0.001 /\left(6.92 \times 10^{6}=\right.$ $1.44 \times 10^{-10}$ seconds.

## TMAX TMax <br> TMAX $=3.0 \mathrm{E}-9$

This command sets the maximum duration (elapsed time) of orbits. Enter TMax in seconds. A common use of the command is to prevent infinite calculations in a system with closed orbits. In the event an orbit exceeds the maximum duration, Trak determines its final position and momentum by an accurate interpolation to TMax. This feature is useful for analyzing isochronous systems. The default value is $T_{\max }=\infty$.

## DMAX DMax <br> DMAX $=15.0$

This command sets a maximum total length for orbits. Enter the distance in units set by DUnit. When the distance exceeds $D_{\max }$, the code determines the stopping point by interpolation so that all orbits have almost exactly the same length. This command gives an alternate way to prevent infinite orbits. The default value is $D_{\max }=\infty$.

## NTRACKMAX $=$ NTrackMax <br> NTRACKMAX $=400$

This command sets the maximum number of integration steps. Its main use is to prevent infinite orbits. The default value is NTrackMax $=20,000$.

The following two commands set specialized controls - it is unlikely that you will need to use them.

## INTERP E [LIN,LSQ] <br> INTERP B [LIN,LSQ] <br> INTERP BB [LIN, LSQ] <br> $\operatorname{INTERP}(\mathrm{B})=\mathrm{LIN}$

By default Trak uses a second-order least-squares fit procedure to calculate electric and applied magnetic field during an integration ( $L S Q$ option). This setting should be suitable for almost all runs. The LIN option activates a simple linear routine that returns a uniform value of electric field, applied magnetic field or beam-generated magnetic field in each element. Although it yields reduced accuracy, the LIN option may be useful if the solution volume includes small enclosed regions. In a cul de sac, the program may have difficulty locating enough points to make the $L S Q$ fit.

## NSEARCH E NSearchE NSEARCH B NSearchB $\operatorname{NSEARCH}(E)=3$

Trak must identify elements in the electric and/or magnetic field meshes occupied by particles during orbit integrations. The procedure is challenging on the conformal meshes used in

TriComp because there is no unique relationship between a node's index and its position. Therefore it is necessary to check individual elements. Furthermore, separate searches must be performed for the calculations of electric and magnetic fields because they are defined on independent meshes. To speed the process Trak uses a fast search procedure. The elements occupied by the orbit starting point are located by full searches on each mesh. In subsequent steps, local searches are made in the vicinity of the last occupied element. The parameter NSearchE governs the width of the local search region in the electric field mesh. For a good choice of $D t$, the code defaults of $N$ Search $E=N$ Search $B=6$ are sufficient. You can speed up integrations by choosing a smaller value. Larger values may be necessary if a mesh contains regions with very small elements.

### 8.5 Stopping conditions

The implementation of precise stopping conditions is a critical component of a charged-particle simulation. For example, you may want to determine whether a particle strikes a detector and then to find the exact particle parameters at the impact point. Similarly, in characterizing a lens we want a precise prediction of beam properties in a plane normal to the axis. This section describes the wide variety of available methods to stop particles in Trak.

We shall first address orbit termination at region surfaces in the finite-element meshes. Regions in the electric and/or magnetic field meshes can be assigned one of three properties that affect particle transport.

- Vacuum. Particles move unimpeded through Vacuum elements.
- Material. Particles stop when they enter a Material element.
- Secondary. This feature applies only to electron tracking. Electrons are re-emitted when they enter a Secondary element. The process of secondary emission is described in detail in Chap. 14.

When a particle enters a Material or Secondary element, Trak employs a sophisticated procedure to project the orbit back to the entry surface to find the final or re-emission position.

Trak makes default assignments of region material properties. In the electric mesh, all elements with $\epsilon_{r}=1.0$ are set as Vacuum, and all elements with fixed potential or $\epsilon_{r} \neq 1.0$ are set as Material. In the magnetic mesh elements with $\mu_{r}=1.0$ are initialized as Vacuum, and elements with fixed vector potential or $\mu_{r} \neq 1.0$ are Material. You can use the following commands to change the assignments.

## VACUUM E RegNo <br> $\operatorname{VACUUM}(E)=2$ <br> VACUUM B RegNo $\operatorname{VACUUM}(B)=5$

These commands set all elements with region number RegNo in the electric or magnetic mesh to the Vacuum condition.

MATERIAL E RegNo
MATERIAL(E) $=4$
MATERIAL B RegNo
$\operatorname{MATERIAL}(B)=1$
This command sets all elements with region number RegNo in the electric or magnetic mesh to the Material condition.

## SECONDARY E RegNo DeltaMax0 EngMax0 <br> SECONDARY(E) = 82.35300 .0 <br> SECONDARY B RegNo DeltaMax0 EngMax0 <br> $\operatorname{SECONDARY}(B)=31.2250 .0$

This command sets all elements with region number RegNo in the electric or magnetic mesh to the Secondary condition. Chapter 14 discusses the properties of secondary emission materials and the interpretations of the additional parameters.

The next set of commands controls the definition of special planes in the solution space to stop, to diagnose or to reflect particles. Normally the location of the plane should be inside the common volume defined by the electric and/or magnetic field meshes. If the script contains the Boundary command in the Fields section, the planes may be located anywhere inside the specified boundary area.

## STOP [UP,DOWN] [X,Y,Z,R] StopPosition <br> STOP(UP, X) $=5.50$

Particle orbits terminate when they cross a stopping plane. Trak projects the orbit back to the plane to find precise values of final position, momentum, total distance and elapsed time.

The Stop command has three parameters with the following options:

- UP, $D O W N$. The string parameter sets the direction of particle motion along the axis normal to the stopping plane.
- $X, Y, Z, R$. The string parameter specifies the axis normal to the stopping plane. Note that the $R$ option can function in simulations with both cylindrical and planar symmetry. In the latter case, the program records parameters when the particle crosses a circular boundary in the $x-y$ plane.
- StopPosition. The real-number parameter is the position of the stopping plane along the normal axis. Enter the value in units set by the current value of DUnit.

As an example, suppose a source at $z=0.0$ creates electrons trapped in an axial magnetic field. We want to stop electrons if they reach an axial displacement of $\pm 5.0 \mathrm{~cm}$ from the source. In this case, we include the commands

```
STOP (UP, Z) = 5.0
STOP (DOWN, Z) = -5.0
```


## DIAG [UP,DOWN] [X,Y,Z,R] DiagPosition <br> DIAG (Up, X) $=4.54$

Trak records a set of final particle parameters that are used in the Diagnostic commands discussed in Chap. 15. The values may also be recorded in a standard particle file using the PartFile command. Sometimes it is useful to record these parameters and then to continue the particle orbits. For example, suppose you want to find the distribution at the waist point of a high-current beam. If the particles stopped at the waist, the electrostatic fields would be incorrect because there was no downstream space-charge assignment. In this case you can define a Diag plane. When a particle crosses such a plane, Trak records interpolated particle parameters in the plane and continues the orbit until a stop condition occurs. Allowed parameters are the same as those for the Stop command. You can define multiple Diag planes - note that parameters are recorded at the last plane encountered.

## RECORD [UP,DOWN] [X,Y,Z,R] RP1 RP2 ... RPN RECORD (Up, Z) = 19.020 .021 .0

With this command you can record precise particle parameters at a number of positions normal to an axis. There are three differences from the Diag command: 1) you can define up to 10 record planes, 2) the information is transferred to multiple PRT files during the orbit integrations and is not available for operations with commands of the Diagnostics section and 3) only a single Record command may appear in the script. The second and third string parameters specify the direction of particle motion and the axis for normal planes. In cylindrical simulations the most common choice would be $U P Z$. Up to 10 real-number parameters may follow giving the positions along the axis for diagnostics. If there are three entries, Trak opens three files with names of the form RunName01.PRT, RunName02.PRT and RunName03.PRT and records values of energy, position and momentum as each particle crosses the corresponding planes. In simulations of the type SCcharge, RelBeam, FEmit and Plasma, data are recorded only on the final cycle.

The following rules apply to the Record command:

- The file may contain only one Record command. Therefore, all planes are normal to a single axis.
- The positions $R P 1, R P 2, \ldots R P N$ must appear in order of increasing value for the $U P$ option or decreasing value for the $D O W N$ option.
- The command must contain between 1 and 10 position values.
- For the $U P$ option, particles with starting positions less than $R P 1$ will not be recorded in any of the files. For the $D O W N$ option, a particle must start at a position above $R P 1$ to be recorded.
- The recording process may not function correctly if the spacing between planes is less than the particle integration step size.


## REFLECT [UP,DOWN] [X,Y,Z,R] ReflectPosition

## REFLECT (Down, Y) $=\mathbf{0 . 0}$

Reflection planes are useful to simulate periodic systems with symmetry in both the fields and particle motions. When a particle crosses a reflection plane, Trak projects its position back to the plane and reverses its momentum normal to the plane. Allowed parameters are the same as those for the Stop and Diag commands. Multiple Reflect, Diag and Stop commands may appear in a control script.

### 8.6 Orbit listings

The final three commands control information that can be recorded during orbit tracking.

## LISTON NStep [P,E,B] LISTON (2, B)

This command initiates records of orbits in the listing file (RUNNAME.TLS). This information is more detailed than the simple coordinate data recorded in the plot file (RUNNAME.TOU). The list option is normally deactivated because complex runs could generate huge listings. The optional parameter NStep is the number of integration steps between records. The optional key symbol $P, E$ or $B$ determines the type of information recorded. Under the $P$ option (the default) the data lines contain the following quantities: step number, elapsed time, coordinates (in units set by the current value of DUnit), total distance, and normalized momentum components $\left(\mathbf{p}_{\text {norm }}=\mathbf{p} / m_{0} c\right)$. In the field modes $(E$ and $B)$ Trak records coordinates of the integration points and the calculated field components. An extract from a file is shown in Table 5. The ListOn command is valuable for debugging runs and checking field interpolations along particle trajectories.

## ORBINFO

Use the OrbInfo command on those occasions when particles mysteriously stop or refuse to move. When the command is issued Trak writes a record in the listing file of the orbit termination status. Table 6 shows an example.

## PLOTOFF

This command suppresses generation of the plot file, RUNNAME.TOU. This feature saves disk space and time if you are making a run with a large number of particles and you are interested only in the starting and ending parameters.

## PLOTSKIP NPlotSkip [NPartSkip]

Trajectories with a large number of steps or distributions with a large number of particles may lead to very large plot files. Use this command to control the size of the TOU file. The parameter NPlotSkip is the number of integration steps per plot vector. The default is NPartPlot $=5$. Use a larger number if the time step is very small (for instance, it a strong magnetic field). Use NPartPlot $=1$ to make a detailed record of trajectories in the TOU file. The optional parameter NPartSkip limits the number of trajectories included in the TOU file. For example, if NPartSkip $=5$, only the trajectories for particles $5,10,15, \ldots$ are included. The default is NPartSkip $=1$ (all trajectories plotted).

Table 5: Extract of orbit list under the E option

| T |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| NTrack | t | x | y | z |
| 0 | $0.0000 \mathrm{E}+00$ | 0 5.0000E-02 | $2.0000 \mathrm{E}+00$ | -2.4990E+00 |
| 5 | 4.0997E-11 | $15.0012 \mathrm{E}-02$ | 2.0000E+00 | -2.2599E+00 |
| 10 | 8.1993E-11 | $15.0105 \mathrm{E}-02$ | 2.0000E+00 | -2.0223E+00 |
| 15 | $1.2299 \mathrm{E}-10$ | 0 5.0400E-02 | 2.0000E+00 | -1.7873E+00 |
| 20 | $1.6399 \mathrm{E}-10$ | 0 5.1073E-02 | 2.0000E+00 | -1.5574E+00 |
| 25 | $2.0498 \mathrm{E}-10$ | 0 5.2292E-02 | $2.0000 \mathrm{E}+00$ | -1.3364E+00 |
| 30 | $2.4598 \mathrm{E}-10$ | 0 5.3994E-02 | 2.0000E+00 | -1.1286E+00 |
| . . |  |  |  |  |
|  | Dist | Ex | Ey | Ez |
|  | $0.0000 \mathrm{E}+00-$ | -9.0412E+00 | $0.0000 \mathrm{E}+00$ | $3.8246 \mathrm{E}+04$ |
|  | $2.3908 \mathrm{E}-01$ | $-2.7417 \mathrm{E}+03$ | $0.0000 \mathrm{E}+00$ | $5.0646 \mathrm{E}+04$ |
|  | $4.7669 \mathrm{E}-01$ | $-6.7280 \mathrm{E}+03$ | $0.0000 \mathrm{E}+00$ | $9.1283 \mathrm{E}+04$ |
|  | 7.1166E-01 - | -1.2867E+04 | $0.0000 \mathrm{E}+00$ | $1.7572 \mathrm{E}+05$ |
|  | $9.4158 \mathrm{E}-01$ | $-1.9363 \mathrm{E}+04$ | $0.0000 \mathrm{E}+00$ | $3.1533 \mathrm{E}+05$ |
|  | $1.1626 \mathrm{E}+00-$ | $-1.7718 \mathrm{E}+04$ | $0.0000 \mathrm{E}+00$ | $4.7408 \mathrm{E}+05$ |
|  | $1.3704 \mathrm{E}+00-2$ | -2.4400E+03 | $0.0000 \mathrm{E}+00$ | $5.5682 \mathrm{E}+05$ |

Table 6: Example of a termination statement
Termination status of particle number 2
Orbit outside the boundary of the electric field solution
Final position: [ 5.4806E-03, 0.0000E+00, 3.9995E+00]
Final momentum: [ -2.0874E-03, 0.0000E+00, 1.9884E-01]
Final kinetic energy: $1.0006 \mathrm{E}+04$

### 8.7 Particle starting times

In Track mode runs that include modulations, the default condition is that all particles start at $t=0.0 \mathrm{~s}$. You can specify individual particle start times relative to the modulation function by adding a column to particle lists or files. In this case, the data lines have the form:

```
PLIST
```



```
END
```

Specify the start time in units of seconds. If an entry is missing, Trak takes the default $t_{s}=0.0$ $s$. When a start time is given, the modulation function is evaluated during an orbit trace as:

$$
\begin{equation*}
f_{e}\left(t+t_{s}\right), \quad f_{b}\left(t+t_{s}\right), \tag{13}
\end{equation*}
$$

where $t$ is the elapsed time from the initiation of the particle trace and $t_{s}$ is the start time. The adjusted time is recorded in particle lists in the TLS file and in the TOU file, Note that any particles that start from an emission surface have $t_{s}=0.0 \mathrm{~s}$.


Figure 19: Field lines generated from an emission surface on the left electrode.

## 9 Tracking electric-field lines

### 9.1 Script commands

This chapter reviews tracing of electric field lines in EStat solutions. Trak employs advanced interpolation techniques to find precise intersection points of field lines with the solution boundary or electrode surfaces. This section discusses control commands for the mode, while the second section describes special features for application to ion mobility mass spectrometry.

Allowed commands in the Particles Fline section serve three functions:

- Set starting points for traces.
- Control the trace integration.
- Specify listing-file diagnostics.

We begin with commands to initiate field line traces.

## FLIST

This command signals that a list of starting positions follows in the control script. Table 7 shows an example of a complete FList structure. The maximum number of lines is 20000. Each data line contains four real numbers. The first three (Xstart, Y start, Zstart) give the initial position in units set by the current value of $D U n i t$. To ensure a valid initial field interpolation, the point must not be inside a fixed-potential element. To avoid errors, make sure that the starting positions are displaced a small distance into the dielectric region from the electrode surface. The quantity Polarity determines the direction of integration. It may assume the

Table 7: Field line list structure

| FLIST |  |  |  |
| :---: | :---: | :---: | :---: |
| * Xstart | Ystart | Zstart | olarity |
| * |  |  |  |
| 0.9999 | 0.0000 | -0.50 | -1.00 |
| 0.9999 | 0.0000 | -0.75 | -1.00 |
| 0.9999 | 0.0000 | -1.00 | -1.00 |
| 0.9999 | 0.0000 | -1.25 | -1.00 |
| 0.9999 | 0.0000 | -1.50 | -1.00 |
| 0.9999 | 0.0000 | -1.75 | -1.00 |
| 0.9999 | 0.0000 | -2.00 | -1.00 |
| 0.9999 | 0.0000 | -2.25 | -1.00 |
| 0.9999 | 0.0000 | -2.50 | -1.00 |
| 0.9999 | 0.0000 | -2.75 | -1.00 |
| END |  |  |  |

values $\pm 1.0$. For Polarity $=+1.0$, the integration proceeds along the direction of positive electric field (i.e., from positive to negative potential). The End command signals the end of the list.

## FFILE FPrefix

## FFILE $=$ PReactor

Trak can read field-line starting points from a file rather than the control script. This feature is useful if there are a large number of starting points or if you want to use the same starting points in several different solutions. The parameter FPrefix is the prefix of a file with a name of the form FPREFIX.FLD in the current directory. Data lines in the file have the same format as those of the FList structure. The file list must terminate with a line containing the End command.

You can also start field lines from emission surfaces using the Emit command. This feature is particularly useful for field lines because we often want to find the destinations of lines that start from different positions on an electrode. The line regions that define emission surfaces can be placed on an electrode or they may follow arbitrary paths in a dielectric region. If an emission segment is on an electrode, Trak picks a starting point slightly displaced into the adjoining dielectric element. The mechanics of identifying an emission surface was described in Sect. 8.3.

## EMIT NReg NPerSeg [Polarity]

EMIT(5) 3-1.0
This command states that facets connecting nodes with region number NReg constitute an emission surface. The integer parameter NPerSeg is the number of segments per facet. The quantity Polarity (equal to $\pm 1.0$ determines the direction of integration. The default is +1.0 .

## START NReg XStart YStart

START(5) $=\mathbf{( 0 . 0}, \mathbf{5 . 0})$ Trak orders emission facets in a continuous line starting from the end. By default, the program starts from the node closest to the axis $\left(y_{\text {min }}\right.$ or $\left.r_{\text {min }}\right)$. If there is any ambiguity, use this command to set the endpoint of the emission surface associated with region NReg.

The following command controls the line integral:

## DS Ds <br> $D S=0.015$

Set the spatial step size for field line integrations. Enter the distance $D s$ in units set by the current value of DUnit. Smaller values of Ds give higher accuracy. If the command does not appear, Trak picks a default equal to the diagonal length of the electrostatic solution space divided by 500.0.

Several commands introduced in Chap. 8 for integration control in the Track mode may also be applied:

## DMAX = DMax <br> NTRACKMAX = NTrackMax <br> NSEARCH E NSearch <br> INTERP E [LIN,LSQ]

Field lines terminate if they leave the volume of the electric field solution or enter a fixedpotential region. You can define additional stopping conditions with the following commands:

## STOP [UP,DOWN] [X,Y,Z,R] StopPosition DIAG [UP,DOWN] [X,Y,Z,R] DiagPosition REFLECT [UP,DOWN] [X,Y,Z,R] ReflectPosition

Finally, the following commands can be used to write diagnostic information to the listing file.

## LISTON NStep LISTON (2)

In contrast to the Track mode, the listing file data lines in the FLine mode always contain the point coordinates and components of the calculated electric field. The key symbols $P, E$ and $B$ are ignored.

## ORBINFO

This command gives a record if the termination status of the field line. To gage the accuracy of the integration, Trak also records the difference in electrostatic potential between the starting and stopping points compared to the line integral $-\int \mathbf{E} \cdot \mathbf{d l}$. Table 8 shows an example of a termination listing.

Table 8: Termination listing for an electric field line

```
Termination status of field line number 3
    Point inside fixed potential region
Final position: [ 1.0000E+00, 0.0000E+00, 1.0001E+00]
Accuracy check
    Phi(Initial): -5.0000E+03
    Phi(Final): 5.0000E+03
    Phi(Final)-Phi(Initial): 1.0000E+04
    Integral -Edl: 9.9991E+03
```



Figure 20: Principle of the ion-mobility time-of-flight spectrometer.

### 9.2 Ion-mobility spectrometry

Trak includes a useful feature to aid in the design of time-of-flight ion-mobility spectrometers. Figure 20 shows the basic principle. The material to be analyzed is ionized in a gas background (typically air at atmospheric pressure). A electric field is applied and the ions drift with velocity vector $\mathbf{v}=\mu \mathbf{E}$, where $\mathbf{E}$ is the electric field vector (in $\mathrm{V} / \mathrm{m}$ ) and $\mu$ is the mobility (in $\mathrm{m}^{2} / \mathrm{V}$-s). Species with different mobilities separate in transit. With a known electric field distribution, the time-of-flight to a detector can be used to infer $\mu$.

For reference, the absolute value of mobility $\mu$ is related to the reduced mobility $\mu_{0}$ (defined at standard temperature and pressure) by:

$$
\begin{equation*}
\mu=\mu_{0}\left(\frac{760}{P}\right)\left(\frac{T+273.15}{273.15}\right) \tag{14}
\end{equation*}
$$

In Eq. 14, $P$ is the pressure in mm of mercury and $T$ is the temperature in ${ }^{\circ} \mathrm{C}$.
Because the drifting ions follow lines of $\mathbf{E}$, the tracking capabilities of the FLine mode are ideal for the application. In addition to calculation of ion trajectories, Trak computes the ion time-of-flight for a given mobility. The time increment $\Delta t$ for an ion to move a distance $\Delta s$ is:

$$
\begin{equation*}
\Delta t=\frac{\Delta s}{|\mathbf{v}|}=\frac{\Delta s}{\mu|\mathbf{E}|} \tag{15}
\end{equation*}
$$

The time-of-flight from point $A$ to point $B$ is therefore:

$$
\begin{equation*}
t_{A B}=\int_{A}^{B} \frac{d s}{\mu|\mathbf{E}|} \tag{16}
\end{equation*}
$$

While tracing a field line Trak computes the following integral to yield the normalized transit time:

$$
\begin{equation*}
\tau_{A B}=\mu t_{A B}=\int_{A}^{B} \frac{d s}{|\mathbf{E}|} \tag{17}
\end{equation*}
$$

The quantity $\tau$ (in $\mathrm{m}^{2} / \mathrm{V}$ ) depends only on the nature of the electric field solution. The properties of the background gas and ions are contained in $\mu$. Therefore, a knowledge of the normalized transit time distribution completely characterizes the performance of a detector for any fill gas or ion species.

Figure 21 shows an example of an ion-mobility spectrometer. An entrance grid, a set of biased rings and a detector plane create a field that increases in the $z$ direction. The goal is to capture ions and to compress the distribution to a small-diameter detector. The figure shows equipotential lines and ion drift orbits (corresponding to electric field lines) with entrance radii in the range $0.0 \leq r \leq 1.2 \mathrm{~cm}$. An orbit with an initial radius of 1.2 cm has radius 0.393 cm at the detector, a 9.3:1 area compression. If the PartList command appears in the Diagnostics section for a calculation in the FLine mode, Trak includes the statistical analysis of Table 9 in the listing file. For the example, the average normalized transit time is $\tau_{\text {avg }}=2.68 \times 10^{-6}$ $\mathrm{m}^{2} / \mathrm{V}$. If the ion mobility is $\mu=1.36 \times 10^{-4} \mathrm{~m}^{2} / \mathrm{V}-\mathrm{s}$, the predicted average transit time is 19.7 ms . The dispersion in normalized transit time is $\Delta \tau=6.03 \times 10^{-8} \mathrm{~m}^{2} / \mathrm{V}$. Therefore, we expect that the field-magnitude and trajectory variations limit the detector resolution to about $R \geq \Delta \tau / \tau_{\text {avg }}=2.25 \%$.


Figure 21: Ion-mobility spectrometer - electrode geometry and ion orbits.

Table 9: Example - statistical analysis for ion-mobility calculations

```
Mobility statistics
Number of values: 12
Normalized transit time (Tau = Int(ds/|E|)
    Tau (average): 2.67762E-06 (m2/V)
    Tau (stddev): 6.02967E-08 (m2/V)
    Tau (minimum): 2.61802E-06 (m2/V)
    Tau (maximum): 2.80662E-06 (m2/V)
Field line length
    D (average): 1.00287E-01 (m)
    D (stddev): 3.18367E-04 (m)
    D (minimum): 9.99953E-02 (m)
    D (maximum): 1.01023E-01 (m)
```


## 10 Space-charge effects and Child-law emission

### 10.1 List input for high-current beams

The SCharge mode is used to model high-current non-relativistic electron and ion beams. In this mode Trak calculates beam space-charge density while tracing particle orbits. Electric fields are then recalculated with the charge contributions of the beam. Several iteration cycles are necessary to find a self-consistent combination of orbits and fields. You can start particles from a list or request that Trak create particles on emission surfaces and assign current to satisfy the Child law (space-charge-limited emission) The data lines of the PList and PFile commands (discussed in Sect. 8.2) have an extra entry to define the current (or current per length in planar simulations) of the model particles.

## PLIST

The PList command signals that a list of starting points follows in the control script. Each data line contains ten real numbers representing the following quantities: mass, charge, energy, start coordinates $(x, y, z)$, direction vector $\left(u_{x}, u_{y}, u_{z}\right)$ and current. Except for the final parameter, the quantities have the same meanings as those discussed for the Track option. In cylindrical simulations the current of a model particle is distributed over an annular region (extending from 0 to $2 \pi$ in $\theta$ ) centered at the particle position $r$. Enter the particle current in amperes. For an injected beam of particles uniformly-spaced in radius with uniform current-density, the particle current should be proportional to $r_{i}$ (the initial particle radius). In planar simulations, enter the current per length (along $z$ ) in units of $\mathrm{A} / \mathrm{m}$. Note that the current is always a positive number. The direction of the current is given by the sign of the quantity charge and the axial velocity of the particle ( $v_{z}$ or $v_{x}$ ). Again, the End command terminates the list.

## PFILE FPrefix

PFILE $=$ Rellnject This command has the same form as the PFile command in the Track mode. The only difference is the addition of the final quantity current in each data line of the file.

Note: In planar simulations in the SCharge mode, the $x$ axis must be the direction of average beam motion. Furthermore, the solution must be symmetric about $y=0.0$. In a typical simulation, you would model only the space $y>0.0$ and apply symmetry conditions at $y=0.0$ (i.e., the Neumann condition for the electrostatic potential and a reflection condition for the particles).

### 10.2 Self-consistent electric field calculations

Self-consistent gun and transport calculations with beam-generated electric fields present a challenge: particle orbits depend on the electric fields while the fields depend upon the orbits through the space charge. Trak employs an iterative approach, the ray-tracing technique, to
solve the boundary-value problem. The program computes particle orbits in the applied electric fields. The space charge associated with the orbits is then used to find a modified solution of the Poisson equation. Next, the orbits are recalculated in the new fields. The process continues over several cycles until the solution converges. The following commands control the cyclic process.

## NCYCLE NCycle NCYCLE $=15$

This command sets the number of orbit-tracking/field-recalculation cycles. The number required for convergence depends on the nature of the problem. A simulation where the beamgenerated electric field makes a small contribution to the total field may converge in a few cycles. On the other hand, a simulation where beam fields predominate (i.e., a beam expanding in a field-free transport region) may require 10-30 cycles. In a multi-cycle run, Trak writes listing information in response to the ListOn command and entries in the plot file only on the final cycle. One sign that a solution has converged is that the electric field recalculation requires fewer than the maximum number of cycles (MaxCycle command).

## AVG Avg <br> AVG $=0.20$

When beam-generated fields are strong it is necessary to adjust the beam space-charge gradually to achieve a convergent solution. The $A v g$ parameter controls the degree of charge deposition. It has a value between 0.0 and 1.0. On any cycle, the space-charge in an element is given by

$$
\begin{equation*}
q_{\text {new }}=(1.0-A v g) \times q_{\text {old }}+A v g \times q_{\text {beam }}, \tag{18}
\end{equation*}
$$

where $q_{\text {old }}$ is the previous value and $q_{\text {beam }}$ is the value calculated from a sum over orbit traces on the present cycle. For a small value of $A v g$ you should use larger values of NCycle. For example, if $A v g=0.15$, then about 30 cycles would be required to ensure that the space-charge density was within $1 \%$ of its equilibrium value. The default is $A v g=0.15$.

Note: The same averaging factor controls current deposition on the electric field mesh in the RelBeam tracking mode.

## AVG AvgInit NChange AvgFinal <br> AVG 0.20100 .05

This form for the $A v g$ command is useful to aid convergence in solutions with complex electron orbits that are sensitive to emission conditions (such as pinched-beam diodes). In this case, high values of $A v g$ give large variations of emitted current between cycles. On the other hand, large values of NCycle are necessary to ensure convergence with low values of $A v g$. A good strategy is to use a relatively high initial value to set up an approximate equilibrium, and then to reduce Avg for good convergence. In this form of the command, the parameter AvgInit is the initial value while AvgFinal is the final value that is applied for cycles NCycle $\geq$ NChange.

For review, the following commands of the Fields section (introduced in Sect. 6.3) control electric field recalculations during each cycle:

MAXCYCLE $=2500$
RESTARGET $=2.0 \mathrm{E}-8$
OMEGA $=1.95$

### 10.3 Child law emission

In the SCharge mode, emission surfaces represent sources of electrons or ions that operate at the space-charge limit. As an example, an emission surface could represent a thermionic cathode when the extracted current density is below the source limit. Trak automatically creates model particles on the emission surface and assigns current to satisfy the the Child law. The condition is that the electric field on the surface approaches zero. The numerical method employed is described in S. Humphries, Numerical modeling of space-charge-limited emission on a conformal triangular mesh, J. Comp. Phys. 125, 488 (1996) included with the Trak package. Here we shall give a brief description of the procedure so you can understand the functions of parameters in the related commands:

- As in the Track and FLine modes, Trak creates a set of emission facets and determines particle initiation points based on the value of NPerSeg.
- A numerical orbit calculation would not be possible if particles were created on the emission surface. The Child condition of zero electric field implies that zero-energy particles would not move, and the calculation would stall.
- To resolve the impasse, Trak creates a generation surface by projecting the particle initiation points a distance $D E m i t$ from the emission surface. Analytic formulas for spacecharge limited flow in a planar gap of width DEmit are employed to find the appropriate current and kinetic energy to assign to model particles at the generation surface. The problem of stalled orbits does not occur because the kinetic energy and electric field are non-zero at the generation surface.
- Trak employs a novel backtracking technique to ensure correct assignment of space charge in the volume between the emission and generation surfaces. The combination of this capability with correction factors for curved electrodes ensures high-accuracy solutions for space-charge-limited flow.
- A program iteration cycle consists of the following operations: 1) create model particles at the generation surface, 2) assign current and kinetic energy based on the present values of local electric field, 3) reverse-track the orbits at fixed energy until they strike the emission surface to set space charge in the gap between the generation and emission surfaces, 4) forward-track the orbits and 5) solve the Poisson equation using the space-charge associated with the orbits. The code makes extensive records in the file FPrefix.TLS so you can check the validity of the process.

The following commands control Child-law emission surfaces.

EMIT(NReg) Mass Charge DEmit [NPerSeg JLimit kTs Ns]<br>$\operatorname{EMIT}(4)=(0.0,-1.0,0.05,3)$

This command identifies the line region NReg as an emission surface. The region must be on the surface of an electrode (fixed-potential region). The parameters Mass and Charge have the same meanings as those in the Emit command of the Track mode. Enter the mass in AMU (atomic mass unit). Trak inserts the value of the electron mass if Mass $=0.0$. Enter the charge of the emitted particles in units of e (i.e., -1.0 for electrons and +1.0 for protons). The quantity DEmit is the distance from the emission surface to the generation surface. Enter the value in units set by the current value of DUnit. The integer parameter NPerSeg is the number of model particles created per facet of the emission surface (default, NPerSeg $=1$ ). The real-number parameter JLimit (in A/m²) is a source limit for current emission and $k T s$ (in eV ) gives the temperature of the source. The integer $N s$ is the splitting parameter with default value $N s=1$. Larger values are useful when $T s>0.0$. A particle is split into $N s$ subparticles. Each subparticle carries a fraction $1 / N s$ of the assigned current and is emitted at a random angle with a distribution width determined by the source temperature. The purpose of the splitting parameter is to improve statistics of downstream particle distributions.

## Notes on the Emit command

- The parameters NPerSeg, JLimit, kTs and $N s$ are optional. If they do not appear, Trak uses default values. If they do appear, they must occupy the correct position in the list. For example, $k T s$ must be the seventh entry after the Emit command. To set $k T s$, you must include values for NPerSeg and JLimit. For space-charge limited emission, use a large dummy value for JLimit.
- The quantity DEmit should be small enough so that the generation surface closely follows the contours of the emission surface. On the other hand, the field interpolations necessary to calculate the Child-law current density will be inaccurate if DEmit is less than the local element width. As a rule, pick DEmit equal to about 1.5 times the local element width. It may be necessary to create small elements with Mesh near the emission surface to achieve a good fit.
- If you set a value for the parameter JLimit, Trak can model mixed space-charge and source-limited emission. The program calculates the Child value at the generation surface and projects it back to the emission surface. The program then chooses the smaller of this value or JLimit. The default value for all emission regions is JLimit $=\infty$.
- If you set a value for the source temperature $k T s$, Trak assigns an angular spread to particles leaving the emission surface. The particles are assumed to have a Maxwell distribution in transverse velocity. The direction of particle emission is determined from a unit vector normal to the emission surface and an angular displacement calculated from the transverse kinetic energy and the longitudinal kinetic energy at the surface. The default value for all emission regions is $k T s=0.0 \mathrm{eV}$.

Use the following equation to convert a value of source temperature in ${ }^{\circ} \mathrm{C}$ to electron volts:

$$
\begin{equation*}
k T_{s}(\mathrm{eV})=\frac{T_{s}\left({ }^{\circ} \mathrm{C}\right)+273}{11,594} \tag{19}
\end{equation*}
$$

The probability distribution of transverse velocity $v_{\perp}$ of particles emitted from a source at temperature $T_{s}$ approximates the Maxwell distribution:

$$
\begin{equation*}
f\left(v_{\perp}\right) d v_{\perp}=v_{\perp}\left(\frac{m}{k T_{s}}\right) \exp \left(-\frac{m v_{\perp}^{2}}{2 k T_{s}}\right) . \tag{20}
\end{equation*}
$$

We can rewrite Eq. 20 in terms of the normalized variable

$$
\begin{equation*}
\chi=\sqrt{\frac{m}{2 k T_{s}}} v_{\perp} \tag{21}
\end{equation*}
$$

as

$$
\begin{equation*}
f(\chi) d \chi=2 \chi \exp \left(-\chi^{2}\right) d \chi \tag{22}
\end{equation*}
$$

The integral of Eq. 22 gives the cumulative probability, a variable in the range from 0.0 to 1.0 :

$$
\begin{equation*}
\int_{0}^{\chi} f(\chi) d \chi=\zeta=1-\exp \left(-\chi^{2}\right) \tag{23}
\end{equation*}
$$

The procedure in Trak is to generate a random value of $\zeta$ and then to find a weighted value of $\chi$ from the inverse of Eq. 23:

$$
\begin{equation*}
\chi=-\frac{\ln (1-\zeta)}{2} . \tag{24}
\end{equation*}
$$

The angle of the particle relative to the surface normal is given by

$$
\begin{equation*}
\Delta \theta \cong \frac{v_{\perp}}{v_{0}}=\chi \sqrt{\frac{k T_{s}}{T_{p}}} \tag{25}
\end{equation*}
$$

where $T_{p}$ is the kinetic energy (in eV ) of the particle at the emission surface. Particles are emitted with a random-uniform distribution of azimuth about the surface normal vector. Note that the derivation is valid in the limit that $v_{\perp} \ll v_{0}$. Trak generates an error message if $k T_{s}$ is too high relative to $T_{p}$. The criterion is that the ratio $k T_{s} / T_{p} \leq 0.40$. If you receive the error message Source temperature too high for the choice of DEmit, either increase DEmit or reduce $T_{s}$. Figure 22 illustrates the effect of source temperature.

## RSEED ISeed1 ISeed2 RSEED 8754662

Set a random seed by supplying two integer values. You can use this command to ensure that a calculation involving emission with a source temperature generates identical results each time it is run. If the command does not appear, the program chooses seed values set by the current clock time to generate statistically independent results for each run.

## SUPPRESS SVal1 SVal2 SVal3 ... <br> SUPPRESS 0.200 .300 .400 .600 .801 .00

The current density assigned at the generation surface must be suppressed below the Child-law value on the first few iteration cycles. Otherwise the initial current based on the applied field values would be too high and the code could oscillate between high and low current solutions on subsequent cycles. To aid convergence Trak applies suppression factors on the first few cycles. The code uses the following default values for space-charge-limited emission:


Figure 22: Particles generated at an emission surface with source temperature. Outward radial flow of electrons across a 5000 V gap with $k T_{s}=0.25 \mathrm{eV}$. Top: equipotential lines and particle orbits. Bottom: axial phase space plot at the outer boundary. The predicted angular divergence is $\Delta \theta \cong \sqrt{k T_{s} / 5000}=0.007$.

| NCycle | Supression value |
| :---: | :---: |
| 1 | 0.250 |
| 2 | 0.300 |
| 3 | 0.500 |
| 4 | 0.750 |
| 5 | 1.000 |
| 6 | 1.000 |
| 7 | 1.000 |
| 8 | 1.000 |
| 9 | 1.000 |
| 10 | 1.000 |

For unusual solutions you can set you own values. Enter from 1 to 10 real numbers in the range 0.0 to 1.0. Any undefined values default to 1.0 .

### 10.4 Relativistic mode

In the SCharge mode, Trak does not perform a detailed calculation of beam-generated magnetic fields. The mode is therefore not appropriate for simulations of relativistic electron guns. On the other hand, Trak can find accurate results for certain types of relativistic-beam transport problems using the relativistic approximation. This approach is faster than the complete calculation under the RelBeam tracking option and may give better accuracy for beams with $\gamma \gg 1.0$.

To begin, we shall review some relativistic beam physics. Consider a circular paraxial electron beam traveling along the $z$ axis in free space. The term paraxial implies that: 1) electrons have about the same axial velocity ( $v_{z} \cong \beta c$ ) and 2 ) orbits make small angles with respect to the axis:

$$
\begin{equation*}
r^{\prime}=d r / d z \ll 1.0 \tag{26}
\end{equation*}
$$

Equation 26 implies that changes in the beam radius $r_{0}$ take place over axial distances much greater than $r_{0}$. Therefore local beam-generated fields are approximately equal to those of an infinite-length beam.

Suppose the beam carries current $I$ and that the space-charge density is a function of radius, $n(r)$. The electric and magnetic fields created by the beam can be determined from Poisson's equation and Ampere's law:

$$
\begin{array}{r}
E_{\perp} \cong 0.0 \\
E_{\perp}(r)=-\frac{e}{2 \pi \epsilon_{0} r} \int_{0}^{r} 2 \pi r^{\prime} d r^{\prime} n\left(r^{\prime}\right) \\
B_{z} \cong 0.0, \\
B_{\perp}=B_{\theta}(r)=-\frac{e \beta c \mu_{0}}{2 \pi r} \int_{0}^{r} 2 \pi r^{\prime} d r^{\prime} n\left(r^{\prime}\right) . \tag{30}
\end{array}
$$

The equations imply that the transverse magnetic force acting on individual electrons is related to the transverse electric force by

$$
\begin{equation*}
F_{B \perp}=-\beta^{2} F_{E \perp} . \tag{31}
\end{equation*}
$$

The quantity $\beta$ is small compared to unity for non-relativistic beams; therefore, the magnetic force can usually be neglected. In contrast, the repulsive electric force and attractive magnetic force are almost balanced for highly relativistic beams ( $\beta \cong 1.0$ ).

The transverse forces of a planar beam also satisfy Eq. 31. In fact, the relationship holds for paraxial beams of any shape and with any nonuniform distribution of space-charge. The equation also holds if we include field contributions of perfectly-conducting boundaries whose dimensions change gradually in the axial direction. We can prove the result by 1) making a Lorentz transformation by velocity $-\beta c$ to the average rest frame of the beam, 2) calculating the electrostatic fields resulting from the stationary distribution of charge, and 3) calculating transformed electric and magnetic field values in the laboratory frame. This derivation also shows that because of Lorentz contraction the criteria underlying paraxial beam motion and the definition of gradual changes in boundary conditions is less stringent for relativistic beams. If $D$ is the transverse scale size of the system and $L$ is the axial distance for a significant change in the beam or boundary dimensions, then Eq. 26 holds if

$$
\begin{equation*}
\frac{R}{\gamma L} \ll 1.0 \tag{32}
\end{equation*}
$$

where $\gamma$ is the relativistic energy factor

$$
\begin{equation*}
\gamma=\frac{1}{\sqrt{1-\beta^{2}}} . \tag{33}
\end{equation*}
$$

The quantity $\gamma$ is related to the rest mass $m_{0}$ and kinetic energy $T$ of the particle by:

$$
\begin{equation*}
\gamma=1+\frac{T}{m_{0} c^{2}} . \tag{34}
\end{equation*}
$$

The theoretical development suggests a strategy to avoid explicit calculations of magnetic fields for relativistic beams. The total transverse force on particles is related to the electric force by:

$$
\begin{equation*}
F_{T \perp}=F_{E \perp}-F_{B \perp}=\left(1-\beta^{2}\right) F_{E \perp}=\frac{F_{E \perp}}{\gamma^{2}} . \tag{35}
\end{equation*}
$$

We simply calculate the electrostatic force and then divide by $\gamma^{2}$ to include the effect of the magnetic field. The relativistic mode holds under the following conditions:

- Transverse electric fields arise almost entirely from the presence of the beam space and surrounding conducting boundaries. This condition does not hold in acceleration gaps where there is a strong applied electric field.
- Beam particles move predominantly in one direction and have approximately the same axial velocity $v_{z} \cong \beta c$.
- The axial scale length for changes in the transverse dimensions of the beam and surrounding boundaries satisfies Eq. 32.

To apply the relativistic approximation in the SCharge mode, simply include the RelMode command in the Particles section.

## RELMODE

When the command is active, Trak divides the transverse electric force ( $F_{r}$ in cylindrical solutions, $F_{y}$ in planar) by $\gamma^{2}$ during orbit calculations.

### 10.5 Restarting a run

Trak has the capability to restore solutions with space-charge and Child-law emission and to proceed over additional iteration cycles. To restart a run, load the electric field file from an initial run. The values of electrostatic potential in this file reflect the presence of space charge. For convergence, the present run should have approximately the same initial conditions as the first run (i.e., electrode potentials, particle lists, emission surfaces,...). In addition to reloading the field solution, you must include the ReStart command in the Particles section. This command initiates two actions that affect runs with emission surfaces:

- Trak automatically sets all suppression factors (SVal1, SVal2, ...) equal to 1.00 because the initial field values are already almost consistent with Child-law conditions.
- Space-charge averaging is not applied on the first cycle because the initial charge density is close to the final converged distribution.


## RESTART

This command signals that an electric field file has been loaded with potential values that are approximately consistent with the presence of beam space charge.

### 10.6 Other commands

The remaining valid commands for the SCharge tracking mode have identical functions to those of the Track mode:

## DT Dt

DT DtRef MASS
TMAX TMax
START(NReg) XStart YStart
NTRACKMAX NTrackMax
DMAX DMax
NSEARCH [E,B] NSearch
INTERP [LIN,LSQ]
MATERIAL [E,B] RegNo
VACUUM [E,B] RegNo
SECONDARY [E,B] RegNo DeltaMax0 EngMax0
STOP [UP,DOWN] [X,Y,Z,R] = Position

DIAG [UP,DOWN] [X,Y,Z,R] = Position REFLECT [UP,DOWN] [X,Y,Z,R] = Position LISTON [NStep] [P,E,B] PLOTOFF

## 11 Tracking relativistic beams

### 11.1 Methods for beam-generated magnetic fields

The simulation of high-current relativistic electron beams is a major challenge for gun-design codes. The drawbacks of approaches to the calculation of beam-generated magnetic fields in previous versions of Trak and other codes are described in the reference S. Humphries and J. Petillo, Laser and Particle Beams 18, (2000), 601 (supplied with the Trak package). The article gives a detailed description of numerical methods applied in the present version of Trak. This section summarizes critical concepts of the method to help you set up effective solutions. The following discussions are oriented to cylindrical beams - note that the method also applies to planar beams with some restrictions.

The approach has several advantages:

- It is largely automatic and requires little input from the user.
- It gives improved accuracy for field calculations, largely eliminating the problem of filamentation in simulations of highly-relativistic beams.
- The method correctly accounts for boundary currents on conductors. As a result, Trak can handle emission from convex or concave cathodes of arbitrary shape as well as beam collection on internal targets.
- It is flexible enough to handle non-laminar beams, counter-flowing particle species and reflex orbits.
- It provides useful diagnostic information on the distribution of beam current striking target surfaces.

The foundation of the method is the calculation of beam-generated magnetic fields on the electric field mesh. There are two motivations for this approach:

- Calculations of electric and magnetic fields are closely coupled, reducing systematic differences.
- Fixed-potential regions in the electric mesh usually correspond to surfaces that carry current and exclude magnetic fields generated by pulsed beams.

The goal of the magnetic field calculation is to find $B_{\theta}(r, z)$ in the propagation volume consistent with the particle orbits. Trak determines values of $B_{\theta}$ at nodes in the electric field mesh and then calculates the field at arbitrary positions by interpolation. The azimuthal magnetic field is related to the enclosed current by:

$$
\begin{equation*}
B_{\theta}(r, z)=\frac{\mu_{0} I_{e n c}(r, z)}{2 \pi r} . \tag{36}
\end{equation*}
$$



Figure 23: Definition of terms for the calculation of beam-generated magnetic field on a conformal mesh. Red lines show the path from a node to the axis along facets. Green lines show facets intersected by an orbit segment.

The quantity $I_{\text {enc }}(z, r)$ is the axial current passing through a plane of radius $r$ at position $z$. The key to the method is therefore finding the total axial current of model particles that pass through circles defined by the mesh nodes.

Figure 23 shows a segment of the orbit of a particle carrying current $I$ moving through the electric field mesh. The segment corresponds to a time step $\Delta t$. The space charge is a volumetric quantity that is conveniently assigned to the elements traversed by the particle. The convention in Trak is to augment the space charge of the element at the segment midpoint by an amount $I \Delta t$. In contrast, the current carried by the particle is a flux that is most conveniently accumulated on the surfaces between elements (facets). Here the convention is to assign the current $I$ to all facets traversed by the particle in the $+z$ direction and a current of $-I$ if the particle moves in $-z$. The reference listed above discusses details of current assignment on conformal triangular meshes to ensure that the condition

$$
\begin{equation*}
\nabla \cdot \mathbf{B}=0 . \tag{37}
\end{equation*}
$$

is always satisfied. The particle tracking process during an iteration cycle gives a set of facet currents that reflect the fluxes of the model particles. To find the current enclosed within a node, we simply trace a path to the axis (red line in Fig. 23) and add the associated facet currents. If the currents satisfy Eq. 37, the result is independent of the choice of path.

Implementation of the method in Trak is complicated by the presence of conductive materials (Fig. 23). There are no particle orbits through these regions; instead, they carry a surface current that depends on the distribution of emitted particles. Trak uses the following procedure to represent surface flows consistent with the condition of continuity of current:

- Facets are divided into three categories: vacuum facets have vacuum elements on each side, collector facets have one vacuum and one material element on each side, and excluded facets are surrounded by material elements.
- Currents are assigned to vacuum facets by the procedure shown in Fig. 23. Currents are assigned to collector facets only when an orbit terminates (i.e., passes from a vacuum to a material element).
- After calculating all orbits, Trak proceeds to the enclosed current calculation. The first step is to set the quantity along the nodes that constitute collector surfaces. The program assumes that a collector surface is a contiguous set of collector facets that connect to the $z$ ( or $x$ ) axis. Trak searches along the axis to find a collector node and then assigns zero enclosed current. The program then searches for the next node connected through a collector facet and assigns the current of the previous node plus the facet current. The program continues in this manner until it reaches the end of the collector surface.
- After processing all collector surfaces connected to the axis, Trak calculates the enclosed current on the remaining nodes connected to vacuum facets. After assigning zero enclosed current to all nodes on the axis, the program works radially outward in layers. When all the nodes in the layer with radial index $L$ are processed, the program moves to layer $L+1$. For each node, the program seeks the shortest connection to a node attached to a vacuum or collector facet in layer $L$. Enclosed current for the node in layer $L+1$ equals the current of the connected node in layer $L$ plus the contribution of the facet. Trak stops if it reaches the boundary of solution volume or if there are no remaining unprocessed nodes.
- The final step is to find values of $B_{\theta}$ at the nodes, inserting the enclosed current and node radius in Eq. 36.

Figure 24 shows sample results of the calculation. The example illustrates a limitation of the method. The calculated fields are valid in the beam propagation region but exhibit dead areas with zero field at large radius. The problem occurs in the region on the right-hand side because the collector surface of the anode does not contact the axis. Therefore, Trak can not assign enclosed current values along the surface. Points in the dead space that lie in the shadow of the anode follow facet paths toward the axis that terminate on anode nodes with zero enclosed current. A similar effect occurs on the cathode side because of the break between the cathode and focusing electrode.

The dead spaces do not affect the simulation because they occur outside the region of beam propagation. On the other hand, there may be cases where a representation of the beamgenerated field is required over the full solution volume. For example, suppose you want to trace electrons emitted from the outer radius of the focusing electrode. In that case, you must construct the mesh so that all nodes of interest are connected to the axis through a chain of collector facets. The example in the next section illustrates such a setup.

The simulation of space-charge-limited electron emission from a convex cathode (Fig. 25) raises an interesting issue. The collector facets on the outside of the cathode are shadowed from the axis. Furthermore, electrons in the plot start from a generation surface and never pass through the cathode surface. In this case, we might ask how Trak assigned facet currents on


Figure 24: Contour lines of $B_{\theta}$ showing missing values in areas shaded by re-entrant collector surfaces that do not connect to the axis.
the cathode to give the valid field solution shown. The answer is that facet current assignment occurred during back-tracking. Recall from Sect. 10.3 that in a calculation with space-chargelimited emission, Trak projects orbits back toward the generation surface at a fixed velocity to ensure correct assignment of space charge in the gap. Facet current assignment is also performed during backtracking. When the particle strikes the cathode, the forward current $I$ is assigned to the intersected facet. Note that the backtracked orbits are not recorded in the TOU file.

The method of current assignment can also be applied to the calculations of beam-generated fields in planar simulations. In this case Trak determines values of $B_{z}$ at node points with average beam motion in the $x$ direction. The calculation is performed in the region $y \geq 0.0$ with the assumption that the enclosed current in $x$ equals zero along the line $y=0.0$. Therefore, the line $y=0.0$ should represent a beam symmetry axis. The line must have the Neumann condition in the EStat calculation and must be defined as a reflection boundary in Trak.

### 11.2 Commands and controls

When Trak enters the RelBeam mode, the program automatically sets up the mechanisms and allots memory to perform the calculation of $B_{\theta}$ on the electric field mesh. Magnetic field contributions are included in the particle equations of motion. With a good electric field mesh and valid choice of emission surface properties, the calculation proceeds automatically with good reliability. There are two commands unique to the RelBeam mode:

## ZEROPOINT ZAxis

## ZEROPOINT -10.0

In the calculation of beam-generated magnetic fields, the zero point is a position on the symmetry axis where $B_{\theta}$ or $B_{z}$ equals zero. The default zero point position is on the axis halfway between $z_{\min }$ and $z_{\max }$ (or $x_{\min }$ and $x_{\max }$ in planar solutions). In cases where upstream and/or


Figure 25: Variations of $B_{\theta}$ for electron emission from a convex cathode.
downstream electrodes intersect the axis, Trak must identify facets on their surfaces to calculate the contribution of boundary currents to the beam-generated magnetic field. The procedure is to start from the zero point and to walk along the axis until the intersection of an electrode is detected. The program then identifies the surface facets of the source or target electrode and marks them accordingly. For some geometries, the default zero point may be inside an electrode and Trak will issue an error message. In this case, use the ZeroPoint command to set a valid position manually. If there is only a source electrode, pick any downstream point on the axis. If there are both source and target electrodes, pick a point between the two. Specify the coordinates in units set by $D U n i t$.

## BACKTRACK

Particles generated from emission surfaces automatically backtrack and make current contributions to collector facets on the source surface. This may not be the case when particles are created with the PList and PFile commands. In this case, the particles from an electrode must be generated within a vacuum element near the fixed-potential surface for a valid electric field interpolation. As a result, the nodes on the electrode surface may have zero values for enclosed current and $B_{\theta}$. The invalid field values would give inaccurate field interpolations near the surface. When the BackTrack command appears, Trak performs an initial backtrack operation on list-input particles. The program reverses the momentum and sign of the current for each particle and follows the orbits until they terminate. Current is assigned to the collector facet intercepted by the particle orbit. Note that backtracking may also improve the distribution of space-charge and the calculation of electric fields near the surface.

The following commands have special interpretations in the RelBeam mode:

## PLIST [Pos, Neg]

## PFILE [Pos, Neg]

## EMIT(NReg) Mass Charge DEmit [NPerSeg JLimit Ts Ns] [Pos,Neg]

Trak determines whether current flows in the $+z$ or $-z$ directions when particles pass through vacuum facets by comparing the directions of the orbit and facet vectors. On the other hand, when a particle strikes a collector facet the program may not be able to determine whether current exits through the right or left-hand boundaries. The axial direction of current along conducting surfaces must be specified for valid orbit solutions in the case of internal collectors or sources. You can add additional string parameters at the end of the PList, PFile and Emit commands to signal whether the associated particle flow on sources and collectors is in the direction from left to right $[\mathrm{Pos}]$ or from right to left $[\mathrm{Neg}]$. The default is Pos.

## RELMODE [Zrmin Zrmax] <br> RELMODE [XRelMin XRelMax] <br> RELMODE $=(20.0040 .00)$

The relativistic mode calculations discussed in Sect.10.4 may seem unnecessary in the RelBeam tracking mode where the program explicitly calculates forces from beam-generated fields. Nonetheless, there is an important reason to include it. For highly relativistic beams ( $\gamma \gg 1.0$ ) passing through transport regions where there is no applied electric field, it is more accurate to determine the transverse force from Eq. 35 than to make separate calculations of the electric and magnetic components. Suppose we wanted to investigate a relativistic electron gun where the beam is matched to a long transport solenoid. The best approach would be to calculate magnetic and electric forces explicitly in the injector region and then to switch to the relativistic mode in the transport region. This form of the RelMode command enables such a calculation. The two real-number parameters define limits along $z$ (cylindrical) or $x$ (planar). The code applies the relativistic mode only in the region $Z_{r \min } \leq z \leq Z_{r \max }$. Enter values in units set by $D U n i t$. The defaults are $Z_{r \min }=-\infty$ and $Z_{r \max }=+\infty$.

### 11.3 Application example - simulation of a pinched electron beam diode

The example described in this section illustrates several Trak techniques. The application, a self-pinched high-intensity electron beam with ion flow effects, is a challenge for a ray-tracing codes. Figure 26 shows the geometry. The anode is a tungsten rod of diameter 1.0 mm located on the axis. The goal is to produce a compressed electron spot on the anode tip with an axial extent less than 1.0 mm . A pulsed voltage of +1.2 MV is applied to the anode. The cathode is a thin coaxial cylinder with an inner radius of 5.0 mm . The figure shows a magnified portion of the simulation volume. The assembly is inside a grounded vacuum chamber with a radius of 35.0 mm . The simulation covers an axial region from -25.0 mm to 25.0 mm .

The file PINCHBEAM.MIN (included in the example library) defines the variable resolution mesh. A line region is defined for electron emission on the cathode surface (red line in Fig. 26). The intense electron flow at the anode immediately creates a surface plasma. Therefore, we include the possibility of space-charge-limited ion emission from the anode tip (green line in Fig. 26).


Figure 26: Geometry of the PINCHBEAM example - magnified view of the acceleration gap. Red line: electron emission region on the cathode. Green line: ion emission region on the anode.

Table 10 shows the file PINCHBEAM.TIN with added line numbers. Note the use of the multiplication factor in the EFile command of Line 2. The solution PINCHDIODE.EOU was generated with an applied potential of 1.0 V . We can then use the normalized solution with a multiplication factor to investigate the effects of changes in applied voltage. The solution must be performed gradually because of the complex electron orbits in the strong beam-generated magnetic fields. Note the large value of NCycle and small value of $A v g$ in Lines 8 and 9. Despite the complexity of particle motion, the solution exhibits good convergence. The emitted current of 16.65 kA in Cycle 33 differs by only about 1 percent from the current in Cycle 32. Lines 10 and 11 defined emission surfaces for the electrons and protons. The string Pos in Line 10 indicates that the electrons move from left to right while Neg in Line 11 signals that ions move from right to left. The zero point (Line 13) for the beam-generated magnetic field is on the axis between the cathode and anode.

The simulation includes a large number of particles (5 per facet) for good statistics. Note that the Mass form of the $D t$ command has been employed because there are two particle species. With regard to the reference time step, the minimum element width in the gap region is 0.1 mm . The velocity of a proton ( 1.0 AMU ) is about $1.52 \times 10^{-7} \mathrm{~m} / \mathrm{s}$, giving a minimum element transit time of $6.6 \times 10^{-12} \mathrm{~s}$. The value $\operatorname{DtRe} f=1.8 \times 10^{-11} \mathrm{~s}$ was sufficient to give a good resolution of the orbits.

The equilibrium current values were 15.20 kA for electrons and 1.12 kA for protons. The effect of ions in neutralizing space-charge was critical to achieve high-current operation and a well-formed pinch. The current dropped by about a factor of 3 if the ions were omitted. The BBBoundary command in Line 16 of the script initiates a listing of accumulated facet currents on the anode rod. The results show that about $78 \%$ of the electron current impinged on the first 1 mm length of the anode. An inspection of the electron orbits in Fig. 27 shows that conditions are marginal for a well-contained pinch. Electrons emitted from the inner edge of

Table 10: Contents of the file PINCHBEAM.TIN

```
01: FIELDS
02: EFile = PINCHDIODE.EOU 1.2E6
03: MaxCycle = 200
04: ResTarget = 1.0E-7
05: DUnit = 1000.0
06: END
07: PARTICLES RELBEAM
08: NCycle = 33
09: Avg = 0.20 (20, 0.05)
10: Emit(5) 0.0 -1.0 0.15 5 POS
11: Emit(6) 1.0 1.0 0.15 5 NEG
12: Dt: 1.2E-11 Mass
13: ZeroPoint: -10.00
14: END
15: DIAGNOSTICS
16: BBDump: PINCHDIODE
17: BBBoundary (6)
18: EDump: PINCHDIODEP
19: END
20: ENDFILE
```



Figure 27: Electron (top) and ion orbits (bottom) for the PINCHBEAM example with NSkip $=5$. Color-coding follows the electrostatic potential.
the cathode tip strike the anode about 2.5 mm from the tip. A small reduction in the cathode inner radius to 4.5 mm gives enhanced current that significantly improves the quality of the focus.

### 11.4 Restarting a RelBeam calculation

The following activities are necessary to restart a calculation in the RelBeam mode: 1) load the electric field file created by the EDump command in a previous run using the EFile command, 2) load values to calculate the beam-generated magnetic field from the same run using the BBFile command, and 3) include the ReStart command in the particles section.

## BBFILE FileName BBFILE PINCHBEAM.BBD

Load quantities to calculate beam-generated magnetic fields generated in a previous solution with the BBDump command. Trak issues an error message if an electric field has not been loaded or if the mesh of the BBD file does not match the electric field mesh.

You can also use the BBFile command in a run to track single particle orbits in the selfconsistent fields of a relativistic beam. In a Track mode calculation, load field information using the EFile, BFile and BBFile commands and start particles of any species using lists or emission surfaces. Trak includes contributions to the magnetic field from all sources. Note that field values will not be changed by the presence of particles in the Track mode.

### 11.5 Space-charge and current neutralization of relativistic electron beams

Although Trak does not include detailed models of plasmas, you can investigate effects of global space-charge and current neutralization. Partial space-charge neutralization of a relativistic electron beam may occur if low-energy plasma electrons are expelled, leaving behind an excess ion density. The space-charge neutralization factor $f_{e}$ is often defined as the ratio of the excess ion density to the beam density. The presence of the ion density reduces the electric field by a factor $\left(1-f_{e}\right)$. For example, if $f_{e}=0.9$, then the loss of plasma electrons reduces the average fields in the beam volume by a factor of 10.0.

To apply local space-charge neutralization, define a dielectric region in the electric field mesh and assign a relative dielectric constant $\epsilon_{r}=1 /\left(1-f_{e}\right)$ in the EStat solution. The dielectric region must be well separated from acceleration gaps so that it does not affect the applied fields. In the subsequent Trak solution, contributions to electric fields from the beam space charge will be reduced by $\left(1-f_{e}\right)$. Be sure to include a command of the form

## VACUUM(E) = NReg

in the Particles section of the Trak file. Here NReg is the region number of the dielectric. This command over-rides the default assignment of the Material attribute to all regions in the electric field mesh that have $\epsilon_{r} \neq 1.0$.

Partial current neutralization may occur if a flow of plasma electrons is driven by the inductive fields of a pulsed beam. The current neutralization factor $f_{m}$ is the ratio of the
average plasma current in the propagation volume to the beam current. The effect is to reduce the beam-generated magnetic fields by a factor $\left(1-f_{m}\right)$.

## CNEUT Fm <br> CNEUT $=0.90$

In response to this command, Trak multiplies all values of $B_{\theta}$ or $B_{z}$ calculated from the beam current by the factor $\left(1-f_{m}\right)$. For relativistic beam propagation in a plasma, the factor lies in the range $0 \leq f_{m} \leq 1.0$.

Although space-charge neutralization may be applied to selected regions through the choice of region dielectric constant, the current neutralization factor applies globally to all active nodes in the electric field mesh. Suppose your goal is to model effects of neutralization on a relativistic electron beam injected through a conducting foil into a gas cell. A possible approach would be to divide the solution into two parts. The first part addresses the vacuum injector with particle orbits terminated at the foil. The PRT file created by the first solution is used as input to the gas cell solution which could include both space-charge neutralization and a global current neutralization factor.

## 12 Field emission of electrons with space-charge effects

In the FEmit particle-tracking mode, Trak can model field emission of non-relativistic electrons. As in the SCharge mode, the program can automatically generate particles over marked source surfaces. The calculations include self-consistent effects of space charge. You can add additional electrons or ions using the PList or PFile commands. There are three differences from the SCharge mode:

- Only electrons may be created on emission surfaces.
- Because the electric field always has a non-zero value on the source surface, it is not necessary to create a generation surface. Electrons are created directly at the source facets.
- Electron current is assigned according to the Fowler-Nordheim equation rather than the Child-law algorithm.

Trak uses Fowler-Nordheim functions tabulated in A. Modinos, Emission Spectroscopy (Plenum Press, New York, 1984), p. 12. If the quantity $E$ is the local electric field amplitude (including space-charge contributions) at a source facet with work function $\phi$, then the current density in $\left(\mathrm{A} / \mathrm{m}^{2}\right)$ is given by

$$
\begin{equation*}
j_{F E}=1.537 \times 10^{-6} \frac{e^{\Gamma} E^{2}}{\phi t(\chi)^{2}}, \tag{38}
\end{equation*}
$$

where

$$
\begin{equation*}
\Gamma=-6.83 \times 10^{9} \frac{\phi^{3 / 2} v(\chi)}{E} \tag{39}
\end{equation*}
$$

and

$$
\begin{equation*}
\chi=3.79 \times 10^{-5} \frac{\sqrt{E}}{\phi} . \tag{40}
\end{equation*}
$$

In the equations $E$ is expressed in $\mathrm{V} / \mathrm{m}$ and $\phi$ in eV . Table 12 lists values for the functions $v(\chi)$ and $t(\chi)$. Trak uses a cubic spline interpolation to find intermediate values.

The set of allowed commands is similar to that for the SCharge mode. The one difference is that the Emit command has different parameters:

Table 11: Fowler-Nordheim functions

| $\chi$ | $v(\chi)$ | $t(\chi)$ |
| :--- | :--- | :--- |
| 0.0000 | 1.0000 | 1.0000 |
| 0.0500 | 0.9948 | 1.0011 |
| 0.1000 | 0.9817 | 1.0036 |
| 0.1500 | 0.9622 | 1.0070 |
| 0.2000 | 0.9370 | 1.0111 |
| 0.2500 | 0.9068 | 1.0157 |
| 0.3000 | 0.8718 | 1.0207 |
| 0.3500 | 0.8323 | 1.0262 |
| 0.4000 | 0.7888 | 1.0319 |
| 0.4500 | 0.7413 | 1.0378 |
| 0.5000 | 0.6900 | 1.0439 |
| 0.5500 | 0.6351 | 1.0502 |
| 0.6000 | 0.5768 | 1.0565 |
| 0.6500 | 0.5132 | 1.0631 |
| 0.7000 | 0.4504 | 1.0697 |
| 0.7500 | 0.3825 | 1.0765 |
| 0.8000 | 0.3117 | 1.0832 |
| 0.8500 | 0.2379 | 1.0900 |
| 0.9000 | 0.1613 | 1.0969 |
| 0.9500 | 0.0820 | 1.1037 |
| 1.0000 | 0.0000 | 1.1107 |

## EMIT WorkFunc [NPerSeg Beta]

EMIT(4) ( 3.56, 2, 1000.0)
This command identifies region number RegNo (integer) as a source surface and sets associated emission properties. Trak issues an error message if the region does not define a valid source surface (i.e., sets of nodes on the edges of facets between Material and Vacuum elements). At least one Emit command is required under the FEmit tracking mode. Up to twenty Emit commands may appear in the Particles section. Because only electrons are allowed, it is not necessary to specify mass and charge of emitted particles. The real-number parameter WorkFunc is the work function $\phi$ in eV. The integer parameter NPerSeg governs how many model electrons are created per surface facet. The optional parameter $\beta$ is a field enhancement factor that may be useful to simulate emission from carbon nanotube assemblies. If $E_{l o c}$ is the local electric field at the facet, then the program uses the quantity $E=\beta E_{l o c}$ in Eqs. 38 through 40.

## SUPPRESS SVal1 SVal2 SVal3 ... <br> SUPPRESS 0.200 .300 .400 .600 .801 .00

Space-charge effects are usually small in field emission problems so the role of the suppression factors discussed in Sect. 10.3 is not as critical. The default values in the FEmit mode are

| NCycle Supression value |  |
| :---: | :---: |
| ======================= |  |
| 1 | 0.500 |
| 2 | 0.750 |
| 3 | 1.000 |
| 4 | 1.000 |

Note that the number of iteration cycles should be in the range NCycle $\geq 3$ for the default values of suppression factors.

The remaining commands allowed in the Particles FEmit section are identical to those in the Particles Track mode:

DT Dt
DT DtRef MASS
TMAX TMax
START(NReg) XStart YStart
NTRACKMAX NTrackMax
DMAX DMax
NSEARCH [E,B] NSearch
INTERP [LIN,LSQ]
MATERIAL [E,B] RegNo
VACUUM [E,B] RegNo
SECONDARY [E,B] RegNo DeltaMax0 EngMax0
STOP [UP,DOWN] [X,Y,Z,R] = Position
DIAG [UP,DOWN] [X,Y,Z,R] = Position
REFLECT [UP,DOWN] [X,Y,Z,R] = Position
LISTON [NStep] [P,E,B]
PLOTOFF

## 13 Extraction of high-current ion beams from a plasma

When modeling electron extraction from a thermionic or field emission cathode, we can assume that the profile of the source surface is specified a priori. Extraction of ions from a plasma is a more difficult challenge because the surface shape that satisfies all physical constraints is not known in advance. In the Plasma mode, Trak performs the Child-law emission calculations of the SCharge mode described in Sect.10.3. In addition, the program automatically flexes the plasma surface to ensure a uniform distribution of current-density. The calculation is complex, so it is important that you understand the physical basis of ion extraction from a plasma and the goals of the calculation. Section 13.1 discusses this topic and summarizes numerical methods applied in Trak. Section 13.2 reviews new commands that appear in the Plasma mode, while Section 13.3 discusses benchmark examples.

### 13.1 Ion extraction from a free plasma surface

This section briefly reviews the physical basis of the Plasma mode in Trak. For a complete discussion of Child-law emission, the Bohm current density and the formation of a plasma meniscus, see S. Humphries, Charged-particle Beams (Wiley, New York, 1990), Chap. 7. This book is included in the Trak package.

To begin, we must define the term free plasma extraction surface. Assume that plasma ions generated by a source expand in a field-free region through an aperture into an acceleration region with an applied electric field (Fig. 29). The position of the extraction surface (the transition between the plasma environment and the vacuum flow region) is determined by a balance between the plasma ion flux (which we shall denote by an effective ion current density $j_{p}$ ) and the extraction current density governed by the Child law, $j_{C}$. In the one-dimensional geometry of Fig. 28, the current density limit for ions with charge-state $Z_{i}$ and mass $m_{i}$ in a gap of width $d$ and applied voltage $V_{0}$ is given by the expression:

$$
\begin{equation*}
j_{C}=\frac{4 \epsilon_{0}}{9} \sqrt{\frac{2 Z_{i} e}{m_{i}}} \frac{V_{0}^{3 / 2}}{d^{2}} \tag{41}
\end{equation*}
$$

If the ion flux exceeds the vacuum current limit $\left(j_{p}>j_{C}\right)$, then the plasma expands to decrease the gap width d until flux balance is achieved: $j_{p}=j_{C}$. In this case, the surface in Fig. 28 moves to the right. Conversely, if $j_{p}<j_{C}$, the surface recedes to the left. In most plasma sources for ion generation, the ion temperature $\left(T_{i}\right)$ is much smaller than the electron temperature $\left(T_{e}\right)$. In this case, the available effective ion current density is given by the Bohm expression:

$$
\begin{equation*}
j_{p} \cong 0.6 e Z_{i} n_{i} \sqrt{k T_{e} / m_{i}} . \tag{42}
\end{equation*}
$$

The Trak model treats a homogeneous plasma (i.e., $j_{p}$ has a uniform value over the extraction surface). Therefore, a Plasma mode simulation has the following primary goal: for given applied voltages and electrode geometry, find a shape of the extraction surface that guarantees a uniform value of $j_{C}$. A critical issue is the nature of the extraction surface at the triple


Figure 28: Terminology for ion extraction from a free plasma surface.


Figure 29: One-dimensional extraction from a free plasma surface.


Figure 30: Balancing plasma flux $j_{p}$ with space-charge-limited flux $j_{C}$ to achieve a smooth connection at the triple point. a) Ideal balance. b) Insufficient plasma flux. c) Excess plasma flux.
point: the intersection of the plasma, the aperture electrode and the vacuum acceleration region (Fig. 28). Figure $30 a$ shows the ideal situation where the values of $j_{p}$ and $j_{C}$ at the triple point allow a smooth connection between the extraction surface and the focusing electrodes. A reduction in $j_{p}$ from the optimum value causes the plasma to recede into the aperture. In this case the focusing electrode acts as an electrostatic shield, giving a large reduction in the field amplitude at the plasma edge. The implication is that the plasma edge is effectively tied to the aperture at the triple point. A low value of $j_{p}$ gives a distorted extraction surface (Fig. 30b) with attendant poor beam optics. Conversely, a value of $j_{p}$ above the optimal value causes the plasma to bulge into the extraction gap resulting in a divergent beam (Fig. 30c). In summary, there are two constraints on an acceptable plasma extraction surface:

- The value of $j_{C}$ must be uniform.
- The plasma surface must make a smooth connection at the triple point.

The combination of the two conditions with specified electrodes and applied voltages defines a unique plasma surface shape and Bohm current density.

Trak follows a multi-step procedure to determine self-consistent plasma surfaces. Although the operations are complex, most of them are performed automatically so that the user need not be concerned with details. The benchmark examples of Sect. 13.3 show that it is relatively easy to set up a Plasma mode calculation.

1. The user creates an electric-field model of the gun geometry in Mesh. The mesh must include a filled (volumetric) region to represent the plasma (Fig. 28). The plasma region must have enough depth (i.e., number of elements parallel to the displacement direction) to accommodate flexing of the surface. The user makes an initial guess of the extraction surface shape (such as a flat plane). The initial surface should connect smoothly to the aperture at the triple point. The plasma region must appear in the Mesh script


Figure 31: Definition of plasma facets (red line) and plasma nodes (yellow dots). Plasma elements are colored violet and vacuum elements are colored blue. Top: Disk plasma with symmetry axis on the lower edge. Bottom: Annular plasma.
before the surrounding aperture region. This ordering ensures that nodes on the shared plasma-aperture surface are associated with the aperture.
2. The user generates an initial electrostatic solution with EStat. The plasma and aperture regions should be assigned the fixed-potential condition with the same value of applied voltage.
3. In Trak, the plasma region is identified by an Emit statement. The program initially sweeps through the mesh to identify facets and nodes of the source surface. Source facets lie between an element with the region number of the plasma and a Vacuum element. Plasma surface nodes lie along the source surface. Figure 31 shows the two possible options for assignment of surface nodes: a) a cylindrical or planar gun where the surface has an axis of symmetry and $b$ ) an annular gun.
4. Trak orders the facets to form a connected set with respect to distance from the axis or a specified start point. The program determines a set of unit vectors normal to the facets
that point out of the plasma region. The vectors are used to construct an emission surface at a distance DEmit from the source surface to carry out the Child-law calculation.
5. Trak performs a calculation of space-charge-limited flow from the initial surface by creating one or more model ions on each facet of the emission surface. The program runs NInit cycles to achieve a stable, converged solution using the same procedure as in the SCharge mode.
6. Trak calculates the current density on source facets by averaging and back-projecting the model particle currents at the emission surface. The variation of current density is smoothed to prevent the unstable growth of ripples in the surface during the adjustment procedure.
7. The value of emitted current density at each surface node $\left(j_{n}\right)$ is computed by averaging the values on adjacent facets. In addition, a node unit vector (pointing out of the plasma) is computed by averaging the vectors of adjacent facets. The position of each node is moved along this vector a distance $\Delta_{n}=(\alpha d / 2)\left(1-j_{n} / j_{o u t}\right)$ The relationship follows from the scaling of Eq. 41. The quantity $d$ is the width of the acceleration gap, $\alpha$ is a safety factor to ensure stability of the calculation, and $j_{\text {out }}$ is the current density on the facet adjacent to the triple point. Normalizing the displacement to $j_{\text {out }}$ ensures that the plasma surface intersects the triple point at a small angle. The direction of the shift is away from the acceleration gap (into the plasma) when $j_{n}>j_{\text {out }}$. In this case the shift gives a local reduction in the space-charge-limited current density.
8. The positions of plasma and vacuum nodes near the plasma surface are relaxed to preserve element integrity.
9. New normal vectors are computed for the displaced facets and the emission surface is reconstructed.
10. Trak performs NCorrect cycles of orbit and electric field recalculation to determine current densities for space-charge-limited flow from the new plasma surface. The program then returns to Step 6 to recalculate the plasma surface based on updated values of current density. The cycle of surface regeneration and solution correction is carried out NSurface times to achieve a convergent solution.

It is important to recognize cases where the Trak model is invalid. The program cannot be applied to systems where there is a strong transverse magnetic field at the extraction surface (i.e., magnetically-insulated ion diodes, transverse extraction from a Penning source,...). In this case, the condition $j_{p}=j_{C}$ may not hold. Nonetheless, Trak can give useful information on plasma extraction from sources with applied magnetic fields (e.g., duoplasmatron,...) as long as the source has sufficient shielding to isolate the magnetic field from the high-voltage extraction gap. The model also does not apply to sources that produce a mixture of ion species or charge states. In this case the behavior of the extraction sheath is more complex than the simple Child-law model. For example, ions with high-charge state may be preferentially extracted. Finally, we should note that the Plasma mode may also be useful in the design of electron guns with thermionic cathodes. Through the iterative procedure, you can determine cathode shapes that will guarantee uniform current density of the extracted beam.

### 13.2 Plasma mode commands

The following commands perform the same function as those described in Chap. 10 for the SCharge mode:

```
AVG = 0.20
MAXCYCLE = 2500
RESTARGET = 2.0E-8
OMEGA = 1.95
START(5) = 0.25, 0.00
RESTART
```

Note the NCycle command is not valid in the Plasma mode. Trak automatically determines NCycle from the parameters supplied to control the plasma surface calculation. Note that you can add list particles with the commands:

## PLIST <br> PFILE

The Emit command has a different format in the Plasma mode.

## EMIT(NReg) Mass Charge DEmit NPerSeg DGap [Ts] $\operatorname{EMIT}(4)=(4.0,1.0,0.05,3,2.50)$

This command identifies the filled region NReg in the electric-field mesh as a plasma. The plasma surface is defined as the boundary of the region adjacent to a Vacuum region. The plasma must be a fixed-potential region. Specifications for the following five parameters are required. The parameters Mass and Charge have the same meaning as in the Emit command of the Track and SCharge modes. Enter the mass in AMU (atomic mass unit). Trak inserts the value for an electron if Mass $=0.0$. Enter the charge of the emitted particles in units of e (i.e., -1.0 for electrons and +1.0 for protons). The quantity DEmit is the distance from the source surface to the emission surface. Enter the value in units set by the present value of DUnit. As a rule of thumb, set $D E$ mit equal to about 1.5-2.0 times the width of elements adjacent to the plasma surface. Large values of DEmit may prevent convergence of the plasma surface search. The integer parameter NPerSeg is the number of model particles created per facet of the plasma surface. The real-number parameter $D G a p$ is the approximate width of the acceleration gap. Enter the value in units set by DUnit. Larger values of DGap may speed the calculation. Reduce DGap if the calculation does not converge. The signs of convergence failure are: 1) a wavy of irregular plasma surface, 2) code termination because of distorted elements. The optional parameter Ts (in eV) equals the tempreature of the plasma to calculate the angular divergence of particles at the emission surface. Trak can handle only a single plasma region in the Plasma mode. Therefore, the Particles section may contain only one Emit command.

The following command controls the plasma surface calculation.

## PLASMAPARAM NSurface NCorrect NInit [NRadius] PLASMAPARAM 4512

The PlasmaParam command has four integer parameters, one of them optional. The quantity NSurface is the number of cycles of plasma surface adjustment. The quantity NCorrect is the number of orbit-field recalculations to determine a stable solution for space-charge-limited flow per surface adjustment. NInit is the number of initial orbit-field calculations before the first surface adjustment. The optional parameter NRadius controls the width of the region near the surface over which mesh smoothing is applied to plasma and vacuum nodes. (Default values: NSurface $=3$, NCorrect $=5$, NInit $=12$, NRadius $=4)$.

In the remainder of this section, we shall discuss how to choose values for the quantities in the PlasmaParam command and how to ensure solution convergence. To begin, the number of required surface adjustments (controlled by NSurface) depends on how much the initial surface must be flexed to achieve uniform current density. The solution will converge faster if you make an improved initial guess of the surface shape based on a previous run. Trak records extensive information on the surface adjustment procedure in the listing file RUNNAME.TLS. The table labeled Adjustment of plasma surface nodes lists the smoothed values of $j_{n}$ used to calculate the displacements $\Delta_{n}$ as well as the initial and final values of the plasma surface node coordinates. Trak also records the root-mean-squared node displacement. This quantity will be small for a convergent solution. Other indications of convergence are: 1) values of $j_{n}$ are almost equal and 2) the total emitted current approaches a fixed value.

Valid position adjustments $\Delta_{n}$ require accurate values for the smoothed, space-chargelimited current density. Therefore, Trak must perform several orbit-field recalculations to update the emitted current density for the new source/emission surface positions. The parameter NCorrect controls the number of orbit-field recalculations per surface adjustment. The value should be large enough to ensure that total emitted current approaches a stable value between surface adjustments. The parameter NInit equals the number of orbit-field recalculations before the first surface adjustment. The number must be sufficient to achieve a converged solution for the initial surface geometry. You can reduce NInit by loading a previously-computed solution for space-charge-limited flow from the initial surface and by using the Restart command.

Finally, the parameter NRadius controls the half-width of the region near the plasma surface over which mesh smoothing occurs. If a plasma node has indices ( $K_{0}, L_{0}$ ), then graded smoothing is applied to nodes in the range $K_{0}-N$ Radius $\leq K \leq K_{0}+N$ Radius, $L_{0}-$ $N$ Radius $\leq L \leq L_{0}+N$ Radius. The value of NRadius must be larger than the number of elements over which the surface is displaced from the initial guess. Increase NRadius if Trak reports an element distortion in response to a surface shift. You can reduce the chances for element distortion by making a better guess of the initial surface.

### 13.3 Application examples

This section describes some simple examples that illustrate the physics of ion extraction from a plasma as well as Trak modeling techniques. Figure 32 shows the geometry of a benchmark calculation for a cylindrical proton gun defined by the files PLASMA01.MIN, PLASMA01.EIN and PLASMA01.TIN. The aperture has a radius of 2.0 cm , the extraction gap has width $d=4.0$ cm and the applied voltage is $V_{0}=50.0 \mathrm{kV}$. The focusing electrode is inclined at an angle


Figure 32: Geometry of the example PLASMA01 with focusing electrode angle $\theta=22.5^{\circ}$. Figure shows the self-consistent plasma surface, equipotential contours and model particle orbits. Dimensions in cm.
$\theta=22.5^{\circ}$ and the cathode is a plane on the right-hand side of the solution volume. With these parameters we expect that the solution will approximate an ideal Pierce gun. Therefore the ion current density $j_{C}$ should be almost uniform over a flat plasma surface that intersects the triple point. The current-density magnitude is given approximately by Eq. $41: j_{C}=380.5 \mathrm{~A} / \mathrm{m}^{2}$. For comparison, the Trak calculation in the Plasma mode gives a surface with a convexity of 0.009 cm on axis and average current density $\overline{j_{C}}=402.6 \mathrm{~A} / \mathrm{m}^{2}$. In the final state, the current density is uniform over the surface to within $\pm 0.06 \%$. The calculation illustrates the stability and convergence of the Plasma mode procedure.

Next, suppose we increase the focus-electrode angle to $30.0^{\circ}$ (example PLASMA02). The extra metal reduces the electric field on the outer edge of the aperture, suppressing the space-charge-limited current density. Therefore, emission is non-uniform over a flat surface that intersects the triple point (Fig. 33). In this case, Trak must flex the plasma to create a concave surface, thereby reducing the current density near the axis. Table 12 shows the Trak input script. The Emit command specifies proton generation using an emission surface a distance $D E$ mit $=0.075 \mathrm{~cm}$ from the source surface. For comparison, the local element width along $z$ is 0.050 cm . Two model particles are created per facet and the gap width is $D G a p=4.0 \mathrm{~cm}$ (Fig. 32). The PlasmaParam command specifies 4 cycles of surface adjustment with 5 orbitfield recalculations for each cycle. There are 12 initial orbit-field recalculations to achieve an accurate starting solution.

The left-hand-side of Fig. 34 shows the final concave shape of the plasma surface along with computed equipotential lines and model particle orbits in the converging beam. The righthand side shows the solution for a shallow focusing-electrode angle $\left(\theta=15.0^{\circ}\right)$. In this case, the electric field magnitude is higher at the outer radius so that the plasma must assume a


Figure 33: Radial variation of current density for example PLASMA02 with $\theta=30.0^{\circ}$. Green curve shows the initial state while the blue curve shows the current density after the iterative plasma surface adjustment.

Table 12: Trak input file PLASMA02.TIN

* FILE: Plasma02.TIN

FIELDS
EFILE: Plasma02.EOU
DUNIT: 100.0
END
PARTICLES Plasma
EMIT(2) 1.01 .00 .07524 .0
PLASMAPARAM 4512
AVG 0.30
END
DIAGNOSTICS
JSOURCE
PARTLIST
EDUMP Plasma02P
END
ENDFILE


Figure 34: Self-consistent plasma surface shape, equipotential lines and model particle orbits. Left: example PLASMA02 with $\theta=30.0^{\circ}$. Right: example PLASMA03 with $\theta=15.0^{\circ}$.
convex shape for uniform current density.
The examples suggest the following logical sequence for the design of a practical cylindrical ion gun:

1. Starting from the Pierce solution $\left(\theta=22.5^{\circ}\right)$ with flat emission surface, we add an exit aperture in the cathode. The effect of the aperture is to reduce the electric-field magnitude on the plasma surface near the axis.
2. To compensate for the reduction in on-axis current density, we increase the angle of the focusing electrode to suppress emission near the outer radius of the plasma surface.
3. A further increase in the focusing electrode angle would give a converging beam. In this case, it is possible to reduce the radius of the exit aperture (Fig. 28).

## 14 Modeling secondary emission of electrons

### 14.1 Models for secondary electron emission

Trak can represent electron secondary-emission processes to model electro-optical devices and collectors for high-power vacuum tubes. These capabilities apply only to electrons and can be used in the Track, SCharge, RelBeam and FEmit modes. In the latter modes the spacecharge of emitted electrons is added to the electric field recalculation. A single model electron orbit can represent a multi-generational set of electrons. Regions with elements corresponding to secondary emitters are defined with the Secondary command. When an electron enters a secondary element, the secondary-emission coefficient $\delta$ is calculated from the incident energy and particle angle relative to the surface at the entrance point. The current of the electron is multiplied by $\delta$ and it is restarted at a point in the vacuum space near the surface entrance point. The kinetic energy of the emitted electron follows a Maxwell distribution with $T_{e}=2.0$ eV . The direction of emission is normal to the electrode surface.

Trak determines the secondary emission coefficient from a parametric model based on work by Jonker [J.L.H. Jonker, Phillips Research Reports 6, 372 (1951), Phillips Research Reports 7, 1 (1952), Phillips Research Reports 12, 249 (1957)] and Vaughn [R.M. Vaughn, IEEE Trans. Electron Devices ED-36, 1963 (1989) and IEEE. Trans. Electron Devices ED-40, 830 (1993)T்he model involves the angle $\alpha$ between the direction of the incident electron and a vector normal to the surface. The defining function for the angular dependence of $\delta$ is

$$
\begin{equation*}
F(\alpha)=\frac{1}{\sqrt{\cos (\alpha)}} \tag{43}
\end{equation*}
$$

The maximum value of secondary coefficient and the corresponding incident electron energy are given by

$$
\begin{align*}
\delta_{m} & =\delta_{m o} F(\alpha),  \tag{44}\\
E_{m} & =E_{m o} F(\alpha), \tag{45}
\end{align*}
$$

where $\delta_{m o}$ and $E_{m o}$ are the values at normal incidence. These quantities are tabulated for a variety of materials in Tables 13 and 14. The secondary emission coefficient as a function of the angle $\alpha$ and kinetic energy $E$ of the incident electron is given approximately as

$$
\begin{equation*}
\delta(\alpha, E) \cong \delta_{m}(\alpha)\left[f \exp ^{(1-f)}\right]^{a} \tag{46}
\end{equation*}
$$

where $f=E / E_{m}(\alpha)$. The parameter $a$ has the value 0.62 for $f<1$ and 0.25 for $f \geq 1$. To prevent infinite values of $\delta$, the code takes $\alpha=80.0^{\circ}$ for orbits with incident angles that exceed $80.0^{\circ}$. The reference S. Humphries, N. Dione and J. Petillo, Secondary-electron emission modeling on a conformal mesh, Proc. WorkShop on RF Superconductivity, Santa Fe, 1999 (included with the Trak package) gives a detailed description of numerical methods used to treat secondary emission in the Trak code.

Table 13: Secondary emission coefficients for elements, adapted from D.R. Lide, ed., Handbook of Chemistry and Physics, 74th Edition (CRC Press, Boca Raton, 1993), 12-107

| Element | $\sigma_{m o}$ | $E_{\text {mo }}$ <br> $(\mathrm{eV})$ | Element | $\sigma_{m o}$ | $E_{m o}$ <br> $(\mathrm{eV})$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Ag | 1.5 | 800 | Li | 0.5 | 85 |
| Al | 1.0 | 300 | Mg | 0.95 | 300 |
| Au | 1.4 | 800 | Mo | 1.25 | 375 |
| B | 1.2 | 150 | Na | 0.82 | 300 |
| Ba | 0.8 | 400 | Nb | 1.2 | 375 |
| Bi | 1.2 | 550 | Ni | 1.3 | 550 |
| Be | 0.5 | 200 | Pb | 1.1 | 500 |
| C (diamond) | 2.8 | 750 | Pd | $>1.3$ | $>250$ |
| C (graphite) | 1.0 | 300 | Pt | 1.8 | 700 |
| C (soot) | 0.45 | 500 | Rb | 0.9 | 350 |
| Cd | 1.1 | 450 | Sb | 1.3 | 600 |
| Co | 1.2 | 600 | Si | 1.1 | 250 |
| Cs | 0.7 | 400 | Sn | 1.35 | 500 |
| Cu | 1.3 | 600 | Ta | 1.3 | 600 |
| Fe | 1.3 | 400 | Th | 1.1 | 800 |
| Ga | 1.55 | 500 | Ti | 0.9 | 280 |
| Ge | 1.15 | 500 | Tl | 1.7 | 650 |
| Hg | 13 | 600 | W | 1.4 | 650 |
| K | 0.7 | 200 | Zr | 1.1 | 350 |

Table 14: Secondary emission coefficients for compounds, adapted from D.R. Lide, ed., Handbook of Chemistry and Physics, 74th Edition (CRC Press, Boca Raton, 1993), 12-107

| Material | $\sigma_{m o}$ | $E_{m o}(\mathrm{eV})$ | Material | $\sigma_{m o}$ | $E_{m o}(\mathrm{eV})$ |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Alkali halides |  |  | Oxides |  |  |
| CsCl | 6.5 |  | Ag2O | 1.0 |  |
| KBr (crystal) | 14 | 1800 | A12O3 (layer) | $2-9$ |  |
| KCl (crystal) | 12 | 1600 | Ba0 (layer) | $2.3-4.8$ | 400 |
| KCl (layer) | 7.5 | 1200 | Be0 | 3.4 | 2000 |
| KI (crystal) | 10 | 1600 | Ca0 | 2.2 | 500 |
| KI (layer) | 5.6 |  | Cu20 | 1.2 | 400 |
| LiF (crystal) | 8.5 |  | Mg0 (crystal) | $20-25$ | 1500 |
| LiF (layer) | 5.6 | 700 | Mg0 (layer) | $3-15$ | $400-1500$ |
| NaBr (crystal) | 24 | 1800 | MoO2 | 1.2 |  |
| NaBr (layer) | 6.3 |  | SiO2 (quartz) | $2.1-4$ | 400 |
| NaCl (crystal) | 14 | 1200 | SnO2 | 3.2 | 640 |
| NaCl (layer) | 6.8 | 600 | Others |  |  |
| NaF (crystal) | 14 | 1200 | BaF2 (layer) | 4.5 |  |
| NaF (layer) | 5.7 |  | CaF2 (layer) | 3.2 |  |
| NaI (crystal) | 19 | 1300 | BiCs3 | 6 | 1000 |
| NaI (layer) | 5.5 |  | BiCs | 1.9 | 1000 |
| RbCl (layer) | 5.8 |  | GeCs | 7 | 700 |
| Sulfides |  |  | Rb3Sb | 7.1 | 450 |
| MoS2 | 1.1 |  | SbCs3 | 6 | 700 |
| PbS | 1.2 | 500 | Mica | 2.4 | 350 |
| WS2 | 1.0 |  | Glasses | $2-3$ | $300-450$ |
| ZnS | 1.8 | 350 |  |  |  |

### 14.2 Control commands

The following commands may appear in the Track, SCharge, RelBeam and FEmit sections.

## SECONDARY [E,B] NReg DeltaMax0 EngMax0 SECONDARY (E,5): 2.45320 .0

This command designates that region $N R e g$ in the electric or magnetic field mesh is a Secondary type and assigns emission parameters. In contrast to the simple Vacuum and Material specifications, the command requires two parameters. The real-number quantity DeltaMax0 is the maximum value of the secondary emission coefficient for normal incidence. The real quantity EngMax0 is the kinetic energy of the incident electron (in eV ) at which the maximum occurs.

## SECONDPARAM KECutOff MinFact <br> SECONDPARAM 1.0 2.0E-3

This command sets global parameters that control the termination of multi-generation electron orbits to prevent infinite calculations. The quantity $K E C u t O f f$ is a cutoff value (in eV ) for kinetic energy. An orbit terminates if the energy of the incident electron falls below this value. The default is $K E C u t O f f=2.5 \mathrm{eV}$. During a multi-generation orbit calculation Trak maintains a quantity MultFact equal to the effective number of electrons in a generation per incident electron. This quantity equals the product of secondary emission coefficients for all collisions with secondary materials, $\operatorname{MultFact}(N)=\delta_{1} \times \delta_{2} \times \ldots \delta_{N}$. An orbit is terminated if the multiplication factor drops below the value MinFact. The default is MinFact $=1.0 \times 10^{-4}$.

SECONDLIST In response to this command Trak writes a detailed record of secondary emission events during an orbit integral to the listing file. In runs with NCycle $>1$, a record is made only on the final cycle.

Finally, additional information on particle multiplication is contained in data written in response to the RegList command in the Diagnostics section.

## 15 Particle and field diagnostics

Trak records information on the calculation in the listing file FPrefix.TLS. After computing particle orbits, the program can perform several diagnostic operations in response to commands in the input file. These are contained in the Diagnostics section that follows the Particles section. After the Diagnostics section (or if there is no section), Trak looks for the EndFile command, closes all files, and terminates operation.

### 15.1 General control commands

Diagnostic commands divide into five classes: 1) general control, 2) electric fields, 3) applied magnetic fields, 4) beam-generated magnetic fields and 5) field-line or particle orbit quantities. There are three general control commands:

## NSCAN NScan <br> NSCAN $=100$

Set the number of intervals for line scans initiated by the EScan, BScan or BBScan commands. The default value is $N S c a n=50$.

## INTERP [E,B,BB] [LIN,LSQ] <br> $\operatorname{INTERP}(B B)=\operatorname{LIN}$

The electric and magnetic field calculations in the EPoint, EScan, BPoint, BScan, BBPoint or $B B S c a n$ commands may employ either the linear or least-squares-fit method. The string parameter may assume the values $L I N$ or $L S Q$. The command affects subsequent field calculations. Multiple Interp commands may appear in the Diagnostics section.

## DUNIT DUnit

DUNIT $=39.37$
Change the unit conversion factor for the input of spatial quantities in the diagnostic commands.

### 15.2 Electric field diagnostics

These commands may be used to record the final state of the electric field. These calculations function only if an electric field mesh has been loaded. Note that calculations are performed on the final field solution which may include the effects of scaling, spatial shifts and beam space charge.

## EDUMP FPrefix <br> EDUMP = KlyMod

Record a file of electric field values with the name FPrefix.EOU in the current directory. The file may be loaded into EStat or Trak for plotting and analysis. It may also be used as input
to a subsequent Trak run. For instance, you may want to generate detailed edge orbits in the self-consistent fields of an ion gun.

EPOINT $=(\mathrm{X}, \mathrm{Y}, \mathrm{Z})$
EPOINT $=(0.0,0.0,12.0)$
Record a computation of the electric field at the point $(X, Y, Z)$ in the listing file using the current interpolation method. Enter the coordinates in units set by the current value of DUnit.

ESCAN (X1, Y1, Z1) (X2, Y2, Z2)
ESCAN (0.0, 0.0, 12.0) (5.0, 0.0, 12.0)
List electric field values along the scan line from $\left(X_{1}, Y_{1}, Z_{1}\right)$ to $\left(X_{2}, Y_{2}, Z_{2}\right)$. Enter the coordinates in units set by DUnit.

### 15.3 Magnetic field diagnostics

The following commands record values of applied magnetic field if a magnetic solution has been loaded with the BFile command. The values reflect the actions of scaling and shift operations.

BDUMP = FPrefix
BDUMP $=$ SolShift
Record a file of the magnetic field values used in the simulation with the name FPrefix.BOU in the current directory. The file may be loaded into BStat or Trak for plotting and analysis. The command functions only if a solution has been loaded with the BFile command.

```
BPOINT = (X, Y, Z)
BPOINT = (3.0, 3.0, 0.0)
```

List the value magnetic field calculated from all sources at the point ( $X, Y, Z$ ). Enter coordinates in units set by the current value of DUnit. Depending on the commands of the Fields section, the calculation may include contributions from a finite-element mesh, a table of on-axis values, uniform field components, or an azimuthal field created by a wire.

BSCAN (X1, Y1, Z1) (X2, Y2, Z2)
BSCAN (2.0, 0.0, -3.0) (2.0, 0.0, 15.0)
List magnetic field values calculated from all sources along the scan line from $\left(X_{1}, Y_{1}, Z_{1}\right)$ to $\left(X_{2}, Y_{2}, Z_{2}\right)$. Enter the coordinates in units set by DUnit.

### 15.4 Diagnostics of beam-generated magnetic fields

The following commands write values of the beam-generated magnetic field. They function only in RelMode calculations.

## BBDUMP $=$ FPrefix <br> BBDUMP $=$ HTest

Write node values used for the calculation of a beam-generated magnetic field to the file FPrefix.BBD in the current directory. The file has a format similar to the output files of EStat and PerMag. For a cylindrical simulation the recorded quantities are $B_{\theta}$ (in tesla) and the enclosed current at the node (in A). The quantities in a planar simulation are $B_{z}$ and the enclosed linear current in A/m. You can load the file in Trak to create plots of the beam-generated magnetic field.

## BBPOINT $=(\mathbf{X}, \mathrm{Y}, \mathbf{Z})$ <br> BBPOINT: 5.5 6.2 12.3

List the beam-generated magnetic field at the point $(X, Y, Z)$. Enter coordinates in units set by DUnit.

```
BBSCAN \(=(\mathrm{X} 1, \mathrm{Y} 1, \mathrm{Z} 1)(\mathrm{X} 2, \mathrm{Y} 2, \mathrm{Z} 2)\)
BBSCAN \(=(2.0,0.0,-5.0)(2.0,0.0,13.0)\)
```

Lists values of the beam-generated magnetic field along the scan line from ( $X_{1}, Y_{1}, Z_{1}$ ) to ( $X_{2}, Y_{2}, Z_{2}$ ). Enter the coordinates in units set by DUnit.

## BBBOUNDARY NReg BBBOUNDARY(5)

Write a list of facet currents along a collector surface composed of nodes with region number NReg. Trak locates the intersection of the collector surface with the axis and then moves radially outward calculating the total enclosed current and current density from the associated facet currents and areas. The routine can provide useful calculations of current density variations on target surfaces. You may want to define special collector surfaces and/or apply the RelBeam mode in non-relativistic calculations to utilize the capabilities of this command.

## CDENS ZPos Rmax NR CDENS XPos Ymax NY CDENS 5.0 1.520

Employ information on the beam-generated magnetic field stored on the electric field mesh to generate a transverse scan of the beam current density. Sometimes, it may be useful to simulate a non-relativistic beam in the RelBeam in order to use this diagnostic. In cylindrical geometries, the parameters are $Z_{p o s}$ (the $z$ position for the scan), $R_{\max }$ (the outer radius for the scan) and $N_{R}$ (the number of radial intervals). The inner scan radius is always taken as the minimum radius of the solution volume (where $\mathrm{B}_{\theta}=0.0$ ). In planar geometries, the parameters are $X_{\text {pos }}$ (the $x$ position for the calculation), $Y_{\max }$ (the outer displacement for the calculation) and $N_{Y}$ (the number of intervals in $y$ ). Trak issues an error message if $Y_{\min } \leq 0.0$. The calculated values may be subject to large numerical errors if the number of model particles is small or if there are accumulated errors in the orbit calculations. Table 15 shows an example of the listing for a cylindrical simulation:

Table 15: Listing created by the CDens command

```
Current density derived from the beam-generated magnetic field
Axial position, X: 5.00000E+00
    r Jz
=======================
1.5000E-02 4.2624E+06
4.5000E-02 3.2274E+06
7.5000E-02 2.9988E+06
1.0500E-01 2.8971E+06
1.3500E-01 2.8448E+06
1.6500E-01 2.9201E+06
1.9500E-01 3.1195E+06
2.2500E-01 3.6695E+06
2.5500E-01 3.3201E+06
2.8500E-01 3.0915E+05
```


### 15.5 Orbit diagnostics

The final set of commands writes information about particle orbits (or field lines) to the listing file. The final positions used for the calculation may depend on the presence of Diag or Stop commands in the Particles section.

## PARTLIST [SymType] PARTLIST Rect

Make a formatted listing of initial and final positions and momenta for a particle simulation. The list contains only coordinate values in a field line simulation. The parameter SymType may have the values $R E C T$ or $C Y L I N$. In the default mode ( $R E C T$ ) components are given in Cartesian coordinates. If SymType $=$ CYLIN, then values are converted to cylindrical components relative to the $z$ axis.

## PARTFILE FPrefix

## PARTFILE $=$ Part02

Write a file FPrefix.PRT of final orbit parameters to the current directory in the standard particle file format. This file can be used as input to a subsequent Trak run or for distribution analyses in GenDist. This command does not function in the FLine mode.

## REGLIST

This command initiates a list of particle collisions with material volumes organized by region. Information includes the total number of hits, the weighted number of particle collisions in secondary simulations, and the total deposited current. Note that region 0 includes all other particle termination events (e.g., left the solution volume, exceeded $T_{\max }, \ldots$ ).

## PARTDIST

Write a list of beam distribution properties using the final orbit parameters. Calculations are performed relative to the $z$ axis, independent of the symmetries of the field solutions. Quantities include the root-mean-squared widths, angular divergences and emittances in the $x$ and $y$ directions. Trak makes a special emittance listing for cylindrical beams, calculating the value corresponding to a uniform azimuthal distribution of model particles. If the simulation involves space charge, the distributions are weighted by the model particle currents. You can perform similar calculations interactively in GenDist by creating a particle output file with the PartFile command.

## DISPLIST

Make a simple listing of initial and final orbit displacements from the axis. In cylindrical simulations the tabulated quantities are $r_{i}$ and $r_{f}$, while $y_{i}$ and $y_{f}$ are recorded for planar simulations. This information can be useful to assess the optical quality of a charged-particle gun. If the gun produces a laminar beam, a plot of $r_{i}-r_{f}$ follows a straight line.

## JSOURCE

Record a list of smoothed current density on emission facets ordered by region. Table 16 shows an example. The smoothing routine uses a least-squares-fit to a fourth-order polynomial. The independent variable is distance from the start point of the region. Only even terms in $r$ (or $y$ ) are used if the emission surfaces contacts an axis of symmetry. In the case of cylindrical solutions, a weighting function proportional to $r$ is applied so that errors in the calculated current density for low-current particles near the axis do not skew the results. Figure 35 illustrates the fitted function for a cylindrical beam.

Table 16: JSource command listing

| --- | Smoothed emission-facet current density --- |  |  |  |
| ---: | ---: | :---: | :---: | :---: | :---: |
| $N$ | NReg | ZAvg | RAvg | JAvg |
| $=========================================$ |  |  |  |  |
| 1 | 2 | $1.009 \mathrm{E}+00$ | $5.000 \mathrm{E}-02$ | $4.020 \mathrm{E}+02$ |
| 2 | 2 | $1.009 \mathrm{E}+00$ | $1.500 \mathrm{E}-01$ | $4.020 \mathrm{E}+02$ |
| 3 | 2 | $1.009 \mathrm{E}+00$ | $2.500 \mathrm{E}-01$ | $4.020 \mathrm{E}+02$ |
| 4 | 2 | $1.008 \mathrm{E}+00$ | $3.500 \mathrm{E}-01$ | $4.020 \mathrm{E}+02$ |
| 5 | 2 | $1.008 \mathrm{E}+00$ | $4.500 \mathrm{E}-01$ | $4.021 \mathrm{E}+02$ |
| 6 | 2 | $1.007 \mathrm{E}+00$ | $5.500 \mathrm{E}-01$ | $4.021 \mathrm{E}+02$ |
| 7 | 2 | $1.007 \mathrm{E}+00$ | $6.500 \mathrm{E}-01$ | $4.021 \mathrm{E}+02$ |
| 8 | 2 | $1.006 \mathrm{E}+00$ | $7.500 \mathrm{E}-01$ | $4.022 \mathrm{E}+02$ |
| 9 | 2 | $1.005 \mathrm{E}+00$ | $8.500 \mathrm{E}-01$ | $4.023 \mathrm{E}+02$ |
| 10 | 2 | $1.005 \mathrm{E}+00$ | $9.500 \mathrm{E}-01$ | $4.023 \mathrm{E}+02$ |
| 11 | 2 | $1.004 \mathrm{E}+00$ | $1.050 \mathrm{E}+00$ | $4.024 \mathrm{E}+02$ |
| 12 | 2 | $1.004 \mathrm{E}+00$ | $1.150 \mathrm{E}+00$ | $4.024 \mathrm{E}+02$ |
| 13 | 2 | $1.004 \mathrm{E}+00$ | $1.250 \mathrm{E}+00$ | $4.024 \mathrm{E}+02$ |
| 14 | 2 | $1.003 \mathrm{E}+00$ | $1.350 \mathrm{E}+00$ | $4.024 \mathrm{E}+02$ |
| 15 | 2 | $1.003 \mathrm{E}+00$ | $1.450 \mathrm{E}+00$ | $4.025 \mathrm{E}+02$ |
| 16 | 2 | $1.003 \mathrm{E}+00$ | $1.550 \mathrm{E}+00$ | $4.024 \mathrm{E}+02$ |
| 17 | 2 | $1.003 \mathrm{E}+00$ | $1.650 \mathrm{E}+00$ | $4.024 \mathrm{E}+02$ |
| 18 | 2 | $1.002 \mathrm{E}+00$ | $1.750 \mathrm{E}+00$ | $4.023 \mathrm{E}+02$ |
| 19 | 2 | $1.001 \mathrm{E}+00$ | $1.850 \mathrm{E}+00$ | $4.023 \mathrm{E}+02$ |
| 20 | 2 | $1.000 \mathrm{E}+00$ | $1.950 \mathrm{E}+00$ | $4.021 \mathrm{E}+02$ |



Figure 35: Weighted current-density smoothing for a cylindrical beam. Blue squares represent values for individual model particles, the red line is a fourth-order fit. Note the effects of small interpolation errors at element boundaries and near the axis.

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